

# Chapter 1: Introduction

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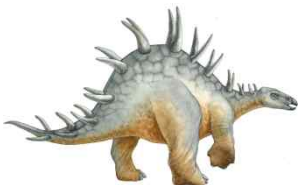
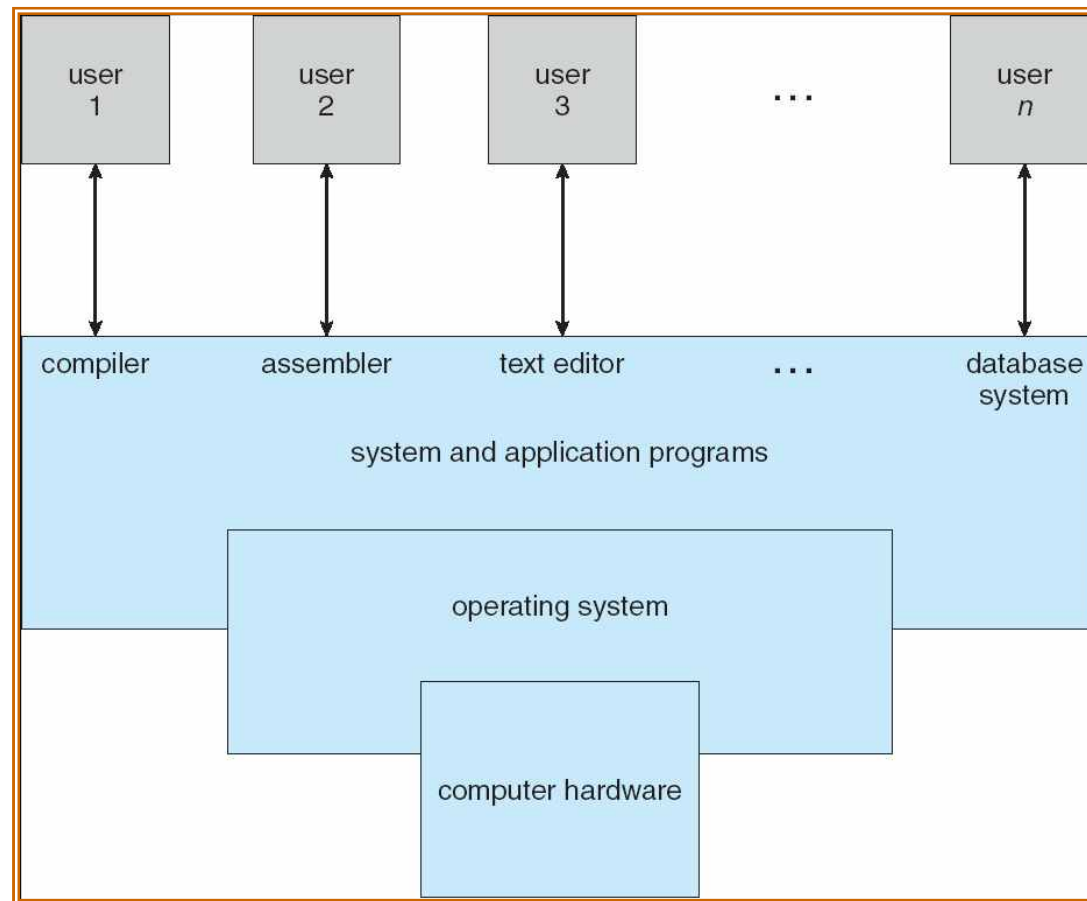
# Operating System이란?

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- computer hardware와 computer user 사이의  
중재자 역할을 수행하는 프로그램
  - The job of the OS is to adapt to hardware. Examples: MS-DOS/Windows, MacOS, Unix, and many more
  
- Operating system goals:
  - Execute user programs and make solving user problems easier.
  - Make the computer system convenient to use.

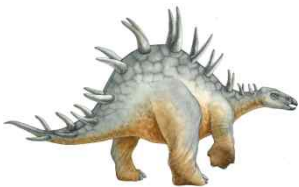


# Abstract View of System Components



# Computer System Components

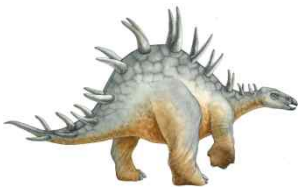
- Computer system의 네가지 구성요소
  - Hardware –basic computing resources를 제공
    - CPU, memory, I/O devices
  - Operating system
    - 다양한 응용과 사용자들간의 하드웨어 사용을 Controls하고 coordinates 함
  - Application programs
    - 사용자의 계산 문제를 풀기 위해 시스템 자원이 어떻게 사용될지를 정의
    - Word processors, compilers, web browsers, database systems, video games
  - Users
    - People, machines, other computers



# Operating System Definitions

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- 운영체제의 정의
- OS is a **resource allocator**
  - Manages all resources
  - Decides between conflicting requests for efficient and fair resource use
- OS is a **control program**
  - Controls execution of programs to prevent errors and improper use of the computer



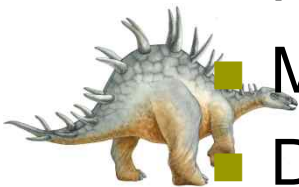
최초의 컴퓨터는?



# OS History

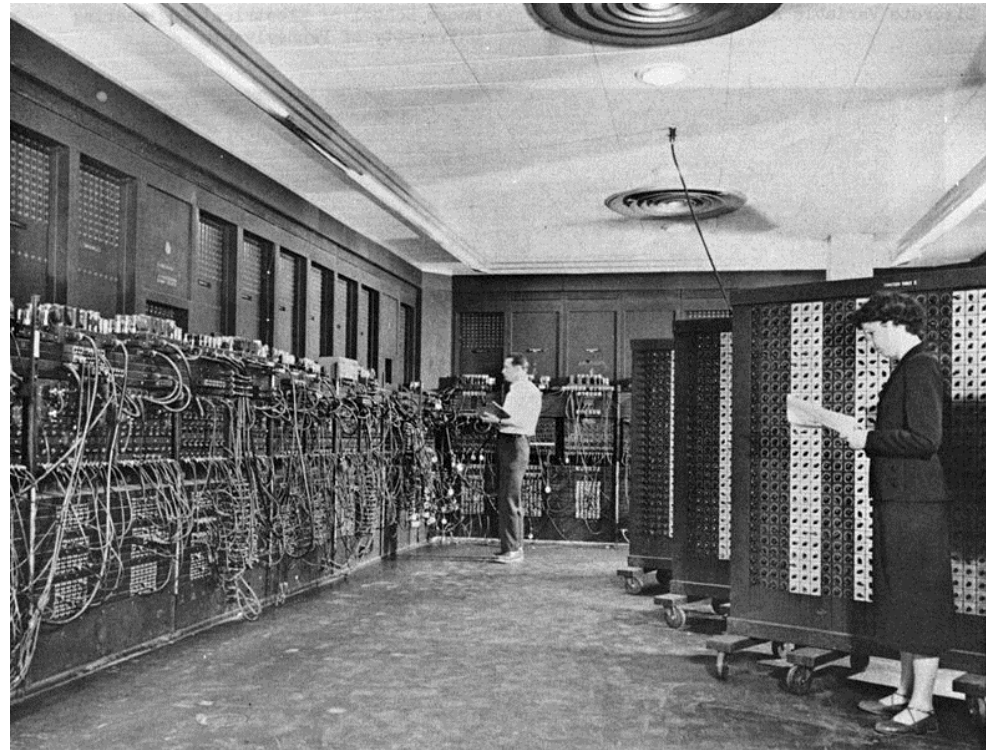
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- Phase 0 : No OS
- Phase 1 : Batch System(일괄처리 시스템)
- Phase 2: Multi-programmed System(다중 프로그램 시스템)
- Phase 3 : Time Sharing System(시분할 시스템)
- Phase 4 : Personal Computing
- tc
  - Real-time System
  - Multi-Processing System
  - Distributed System

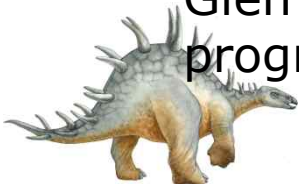


# OS History – ENIAC의 프로그래밍과 OS?

- 최초의 다목적 컴퓨터(ENIAC)에서 프로그래밍은?
  - 1946-1955
  - 10진수 내장 프로그래밍



Glen Beck (background) and Betty Snyder (foreground)  
program the **ENIAC** in BRL building 328



<http://en.wikipedia.org/wiki/ENIAC>





# OS History – ENIAC의 프로그래밍과 OS?



Irwin Goldstein (foreground) sets the switches on one of the ENIAC's function tables at the Moore School of Electrical Engineering



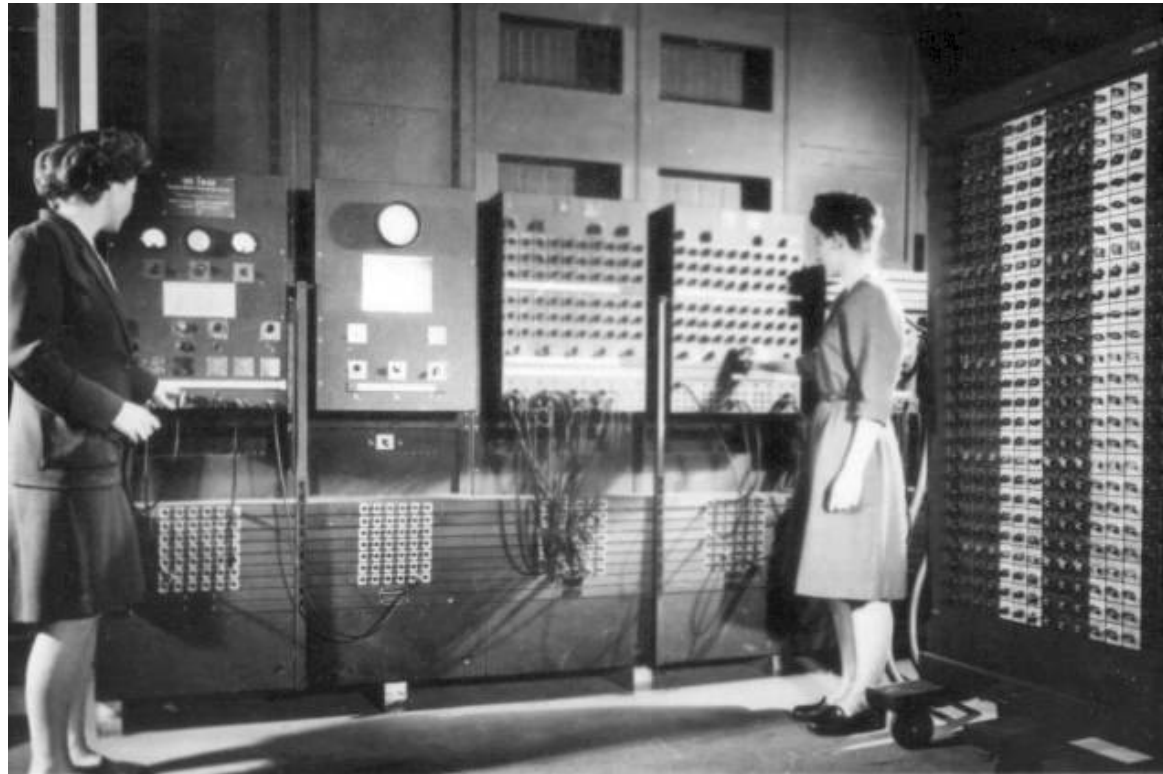
Detail of the back of a panel of ENIAC, showing vacuum tubes.





# OS History – ENIAC의 프로그래밍과 OS?

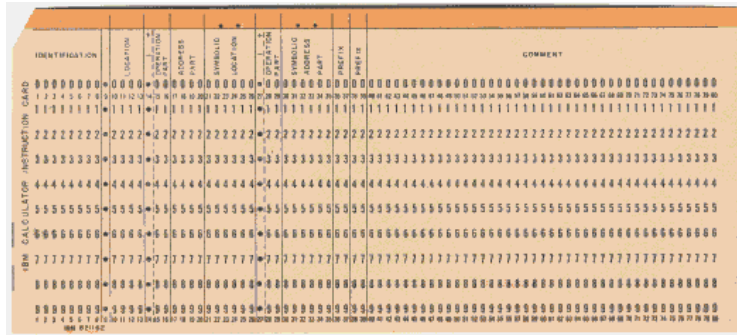
- 최초의 다목적 컴퓨터에서 Operating 은?



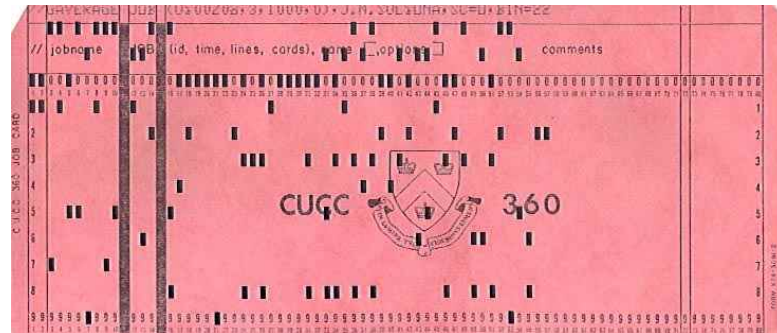
Two women operating the ENIAC's main control panel while the machine was still located at the Moore School



# OS History-Batch System



Punch Card의 예



Punch Card의 예



Punch Card 작업을 하는 사람(IBM)



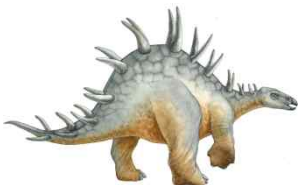
Punch Card 입력 컴퓨터(IBM)



# OS History-Batch System

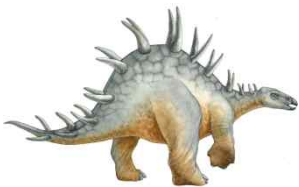
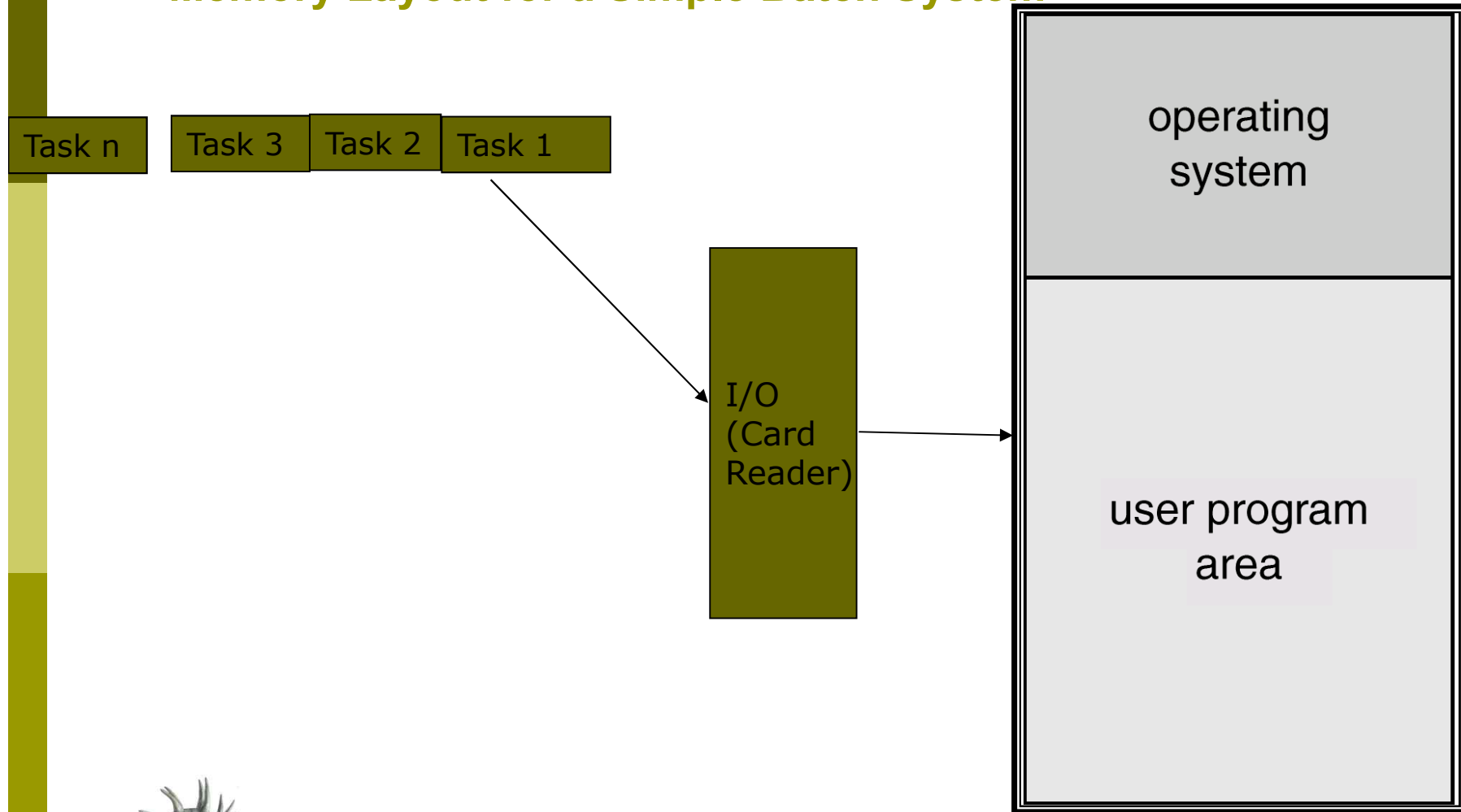
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- Reduce setup time by batching similar jobs
- Automatic **job sequencing** – automatically transfers control from one job to another. First rudimentary operating system.
  - 예) CPU와 I/O간(Card Reader)의 처리속도 차이 존재
    - CPU : 초당 수천개
    - Card Reader : 초당 20장(분당 1200장)
- Resident monitor
  - initial control in monitor
  - control transfers to job
  - when job completes control transfers back to monitor



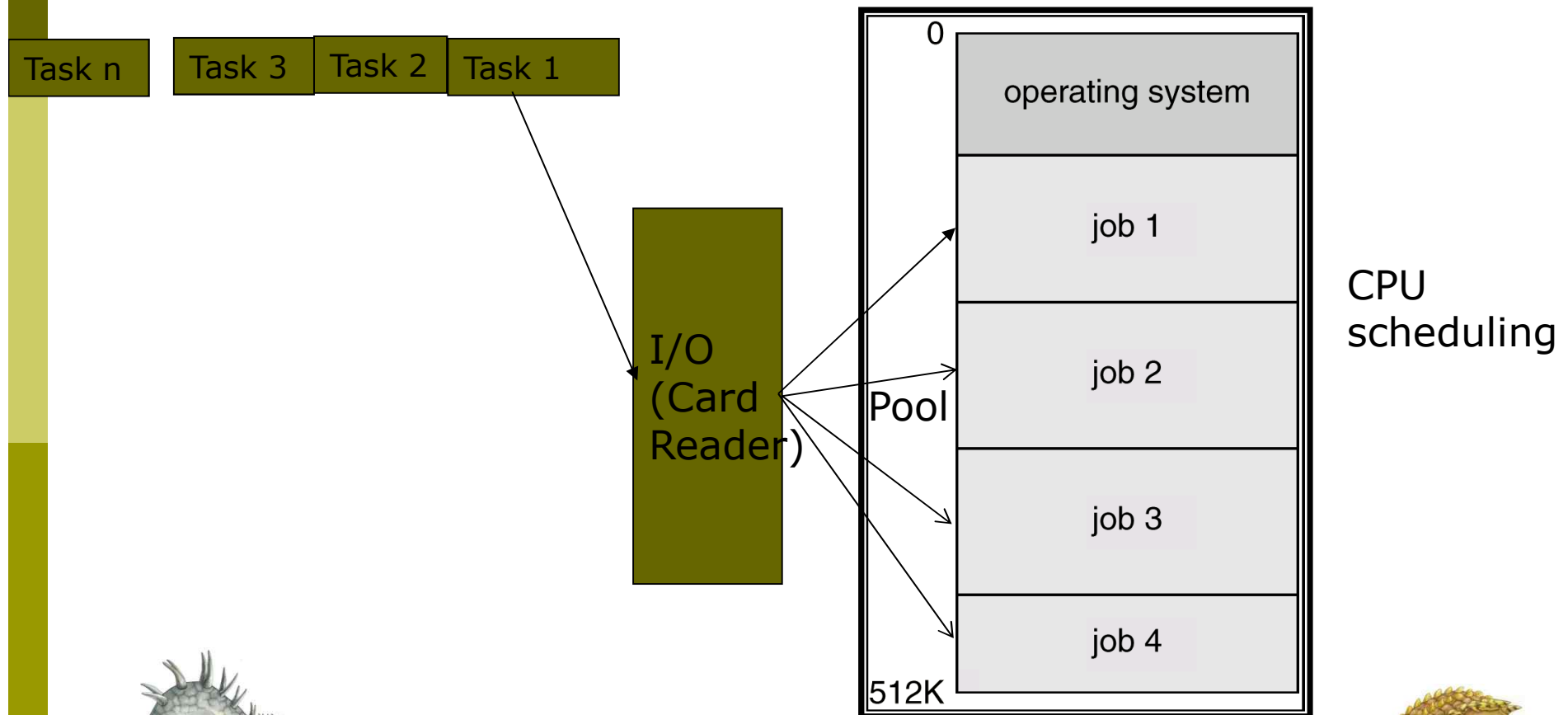
# OS History - Batch System

## Memory Layout for a Simple Batch System



# OS History – Multiprogrammed Systems

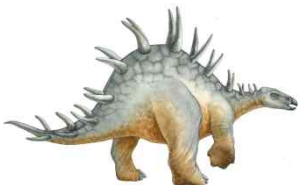
Several jobs are kept in main memory at the same time, and the CPU is multiplexed among them.



# OS History – Multiprogrammed Systems

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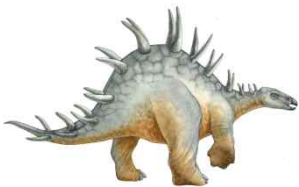
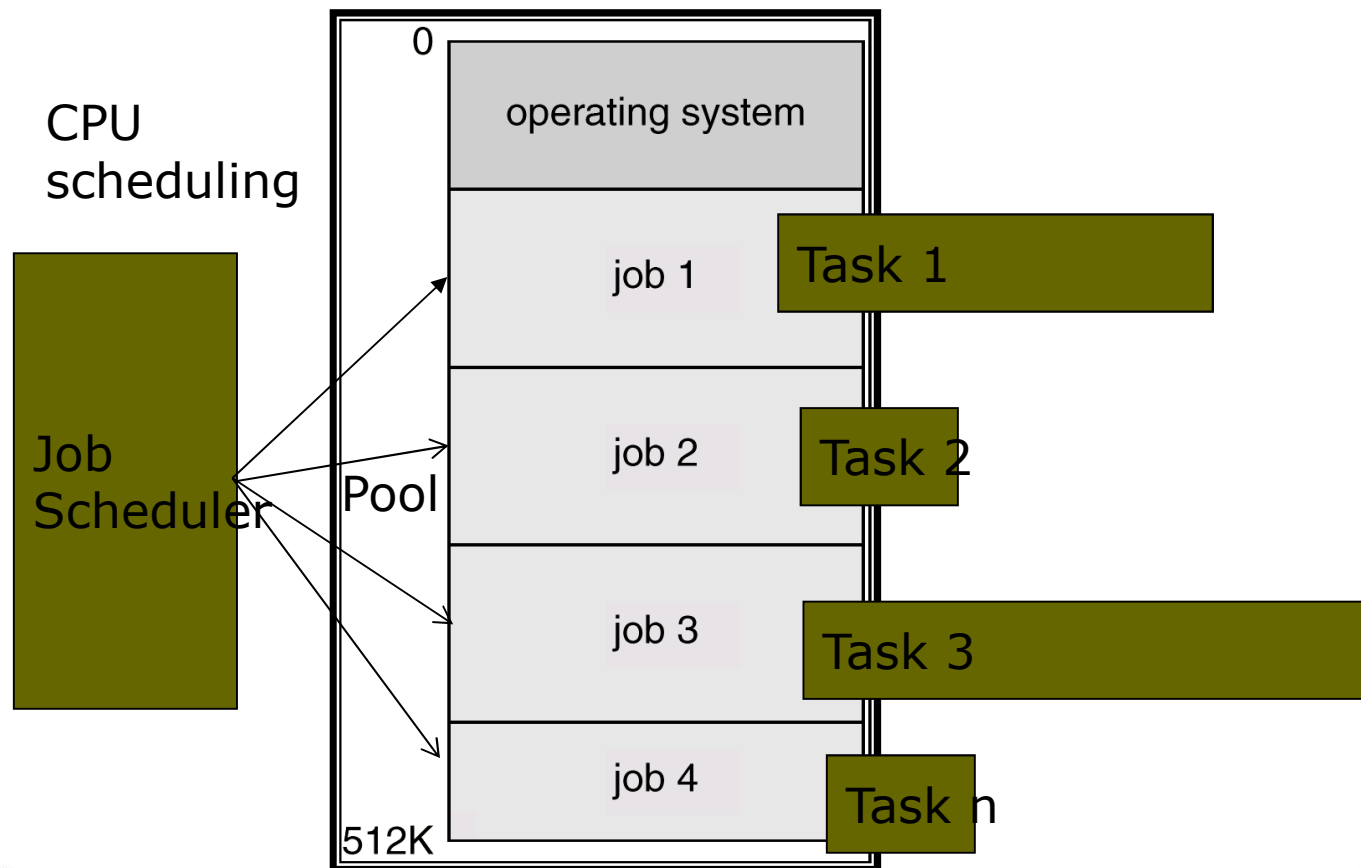
- OS Features Needed for Multiprogramming
  - I/O routine supplied by the system.
  - Memory management
    - the system must allocate the memory to several jobs.
  - CPU scheduling
    - the system must choose among several jobs ready to run.
  - Allocation of devices.





# OS History - Time-Sharing Systems

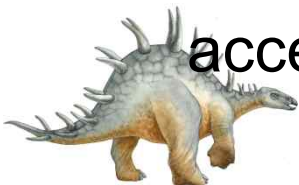
Minimize **Response Time!**



# Time-Sharing Systems–Interactive Computing

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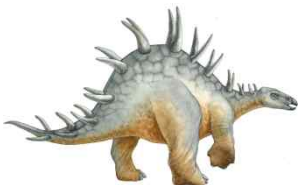
- ❑ The CPU is multiplexed among several jobs that are kept in memory and on disk (**the CPU is allocated to a job only if the job is in memory**).
- ❑ A job swapped in and out of memory to the disk.
  - **Swap-In**
  - **Swap-Out**
- ❑ On-line communication between the user and the system is provided;
  - when the operating system finishes the execution of one command, it seeks the next “control statement” from the user’s keyboard.
- ❑ On-line system must be available for users to access data and code.



# Desktop Systems

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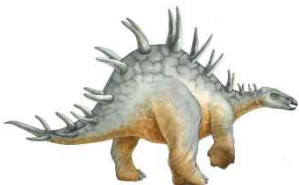
- ❑ *Personal computers* – computer system dedicated to a single user.
- ❑ I/O devices – keyboards, mice, display screens, small printers.
- ❑ User convenience and responsiveness.
- ❑ Can adopt technology developed for larger operating system' often individuals have sole use of computer and do not need advanced CPU utilization of protection features.
- ❑ May run several different types of operating systems (Windows, MacOS, UNIX, Linux)



# Parallel Systems

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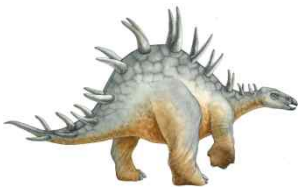
- ❑ **Multiprocessor systems** with more than one CPU in close communication.
- ❑ *Tightly coupled system* – processors share memory and a clock; communication usually takes place through the shared memory.
- ❑ Advantages of parallel system:
  - Increased *throughput*
  - Economical
  - Increased reliability
    - ❑ graceful degradation
    - ❑ fail-soft systems



# Parallel Systems (Cont.)

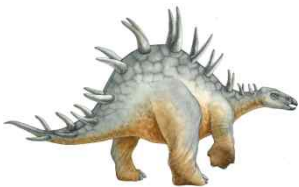
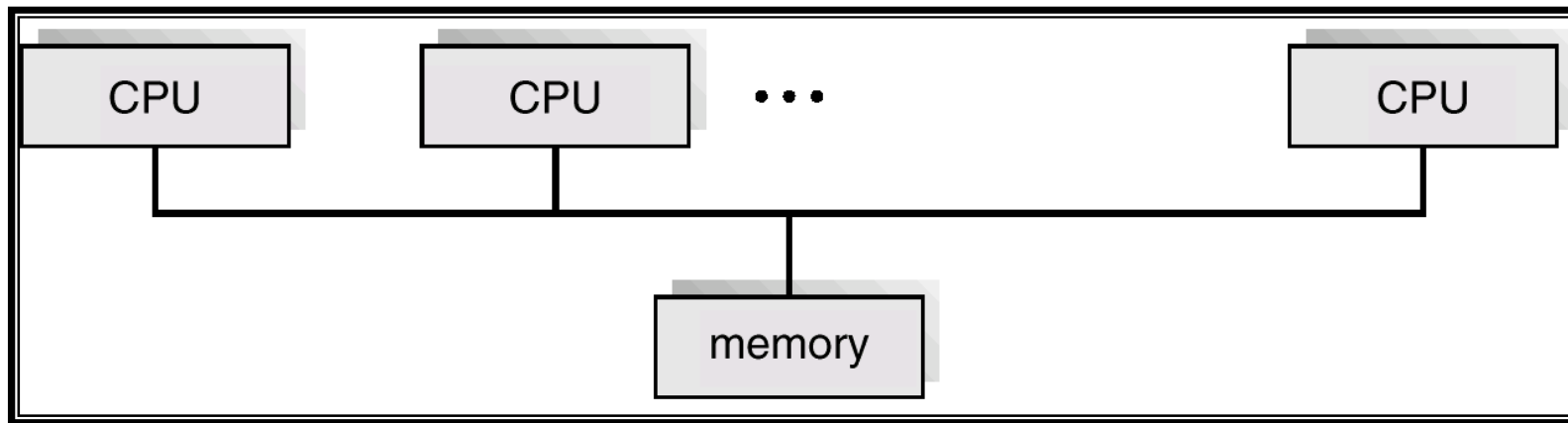
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- *Symmetric multiprocessing (SMP)*
  - Each processor runs an identical copy of the operating system.
  - Many processes can run at once without performance deterioration.
  - Most modern operating systems support SMP
  
- *Asymmetric multiprocessing*
  - Each processor is assigned a specific task; master processor schedules and allocates work to slave processors.
  - More common in extremely large systems



# Symmetric Multiprocessing Architecture

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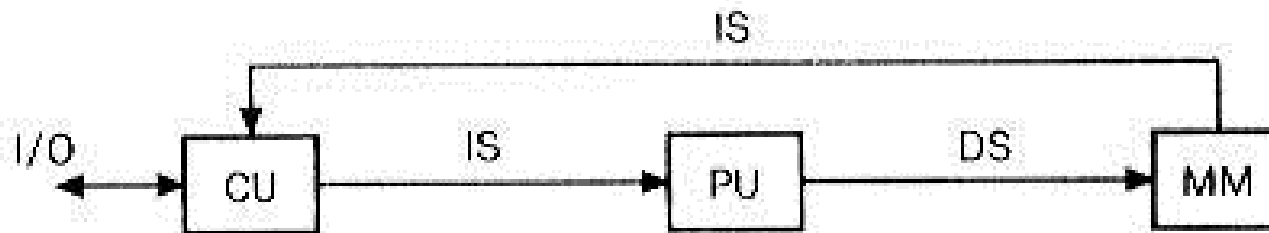


# 대칭적 다중처리(SMP : Symmetric Multiprocessing)

## □ 컴퓨터 시스템의 분류 (by Flynn)

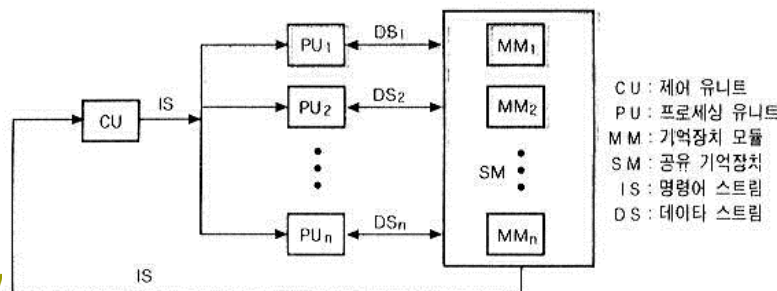
### ■ Single Instruction Single Data (SISD) stream

- 단일 처리기가 한 메모리에 저장된 데이터를 처리하기 위해 단일 명령 스트림을 수행



### ■ Single Instruction Multiple Data (SIMD) stream

- 각 (동일) 명령이 서로 다른 데이터 집합에 대하여 서로 다른 처리기에 의해 수행
- 벡터 및 배열 처리기 (vector and array processors)
- Pentium 처리기의 superscalar 구조



# 대칭적 다중처리 (계속)

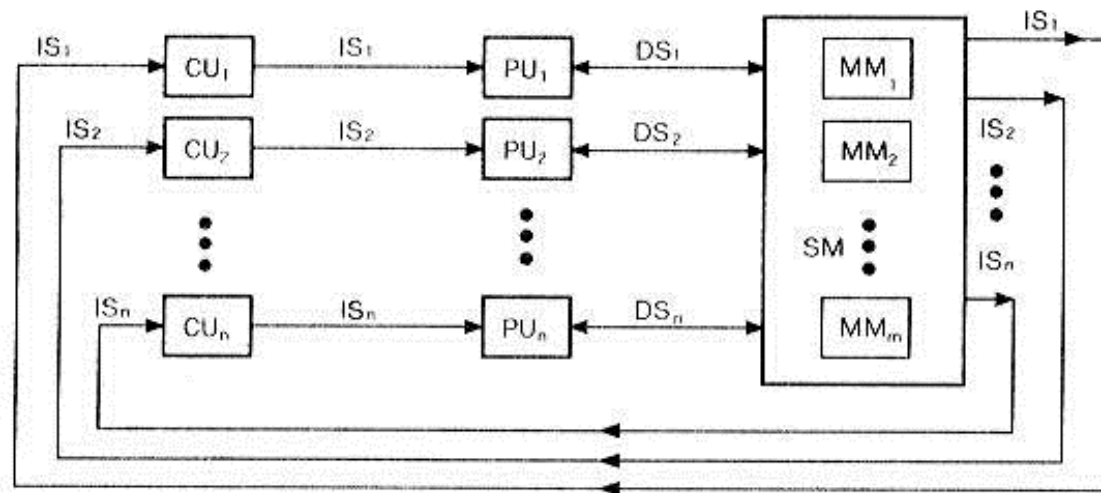
## □ 컴퓨터 시스템의 분류 (by Flynn) (계속)

### ■ Multiple Instruction Single Data (MISD) stream

- (같은) 일련의 데이터가 처리기들의 집합에 전송되고, 각 처리기는 서로 다른 명령을 수행
- 지금까지 구현된 적이 없음

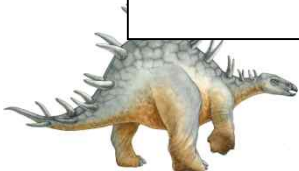
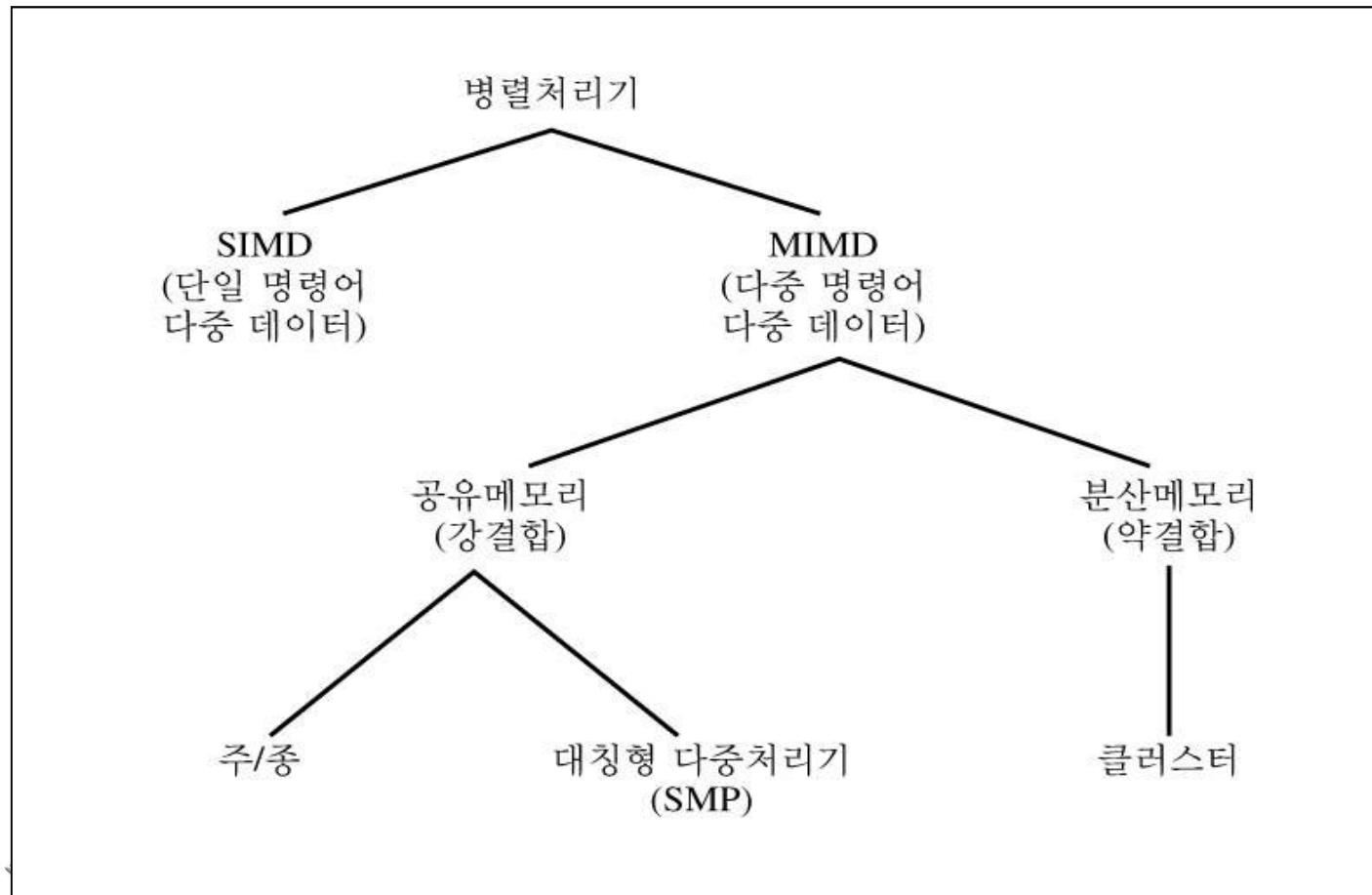
### ■ Multiple Instruction Multiple Data (MIMD) stream

- 다수의 처리기가 서로 다른 데이터 집합에 대하여 서로 다른 일련의 명령어들을 동시에 수행



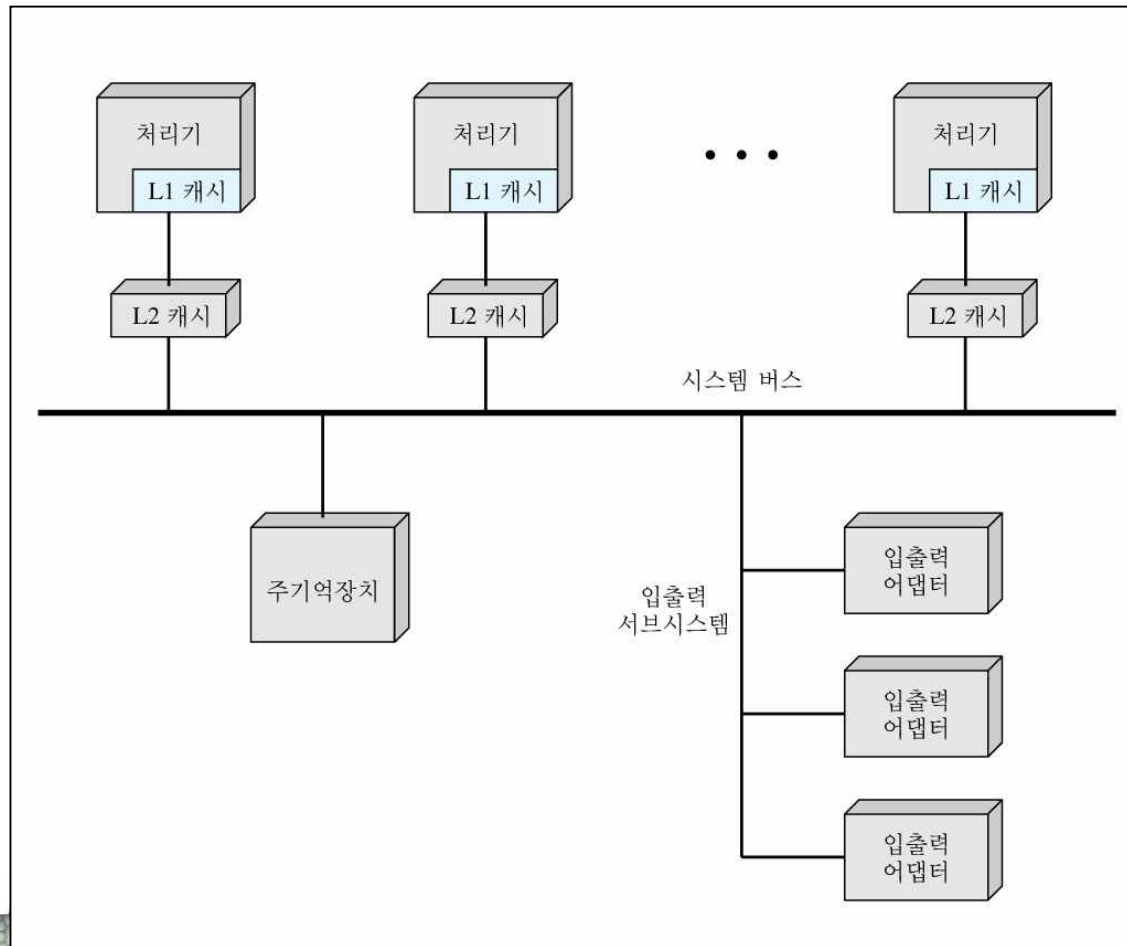
# 대칭적 다중처리 (계속)

## ▣ 병렬 처리기들의 분류 (Categories of Parallel Processors)

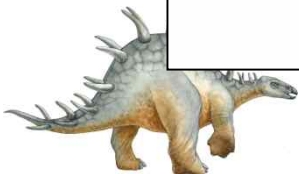


# 대칭적 다중처리 (계속)

## □ SMP 구성



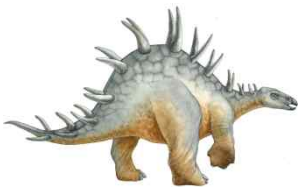
← 캐시 일관성 문제



# 대칭적 다중처리 (계속)

## □ SMP를 위한 OS 설계 시 고려 사항

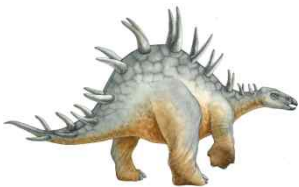
- 목적: 사용자가 다중프로그래밍 단일처리기 시스템(multiprogramming uniprocessor system)과 동일한 관점을 가질 수 있게 자원을 관리
- 동시적 병행(simultaneous concurrent) 프로세스 또는 스레드
  - 재진입(reentrant) 커널 코드
  - 분리된(separated) 커널 자료 구조
- SMP를 위한 프로세스(스레드) 스케줄링
  - 전역 큐 / 지역 큐
  - 집단 스케줄링(gang scheduling)
  - 캐쉬 친화성(cache affinity)



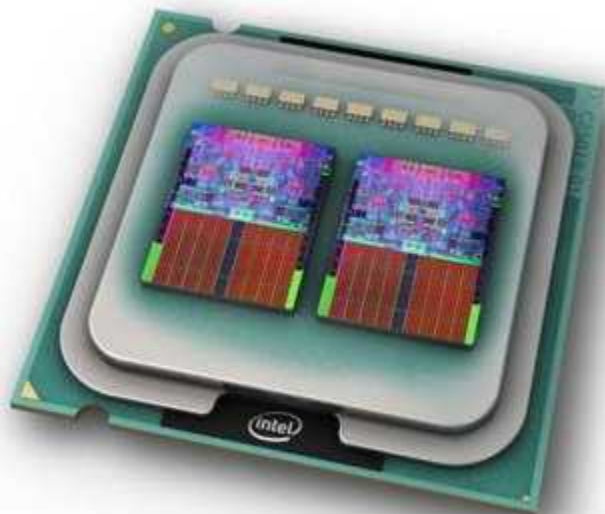
# 대칭적 다중처리 (계속)

## □ SMP를 위한 OS 설계 시 고려 사항(계속)

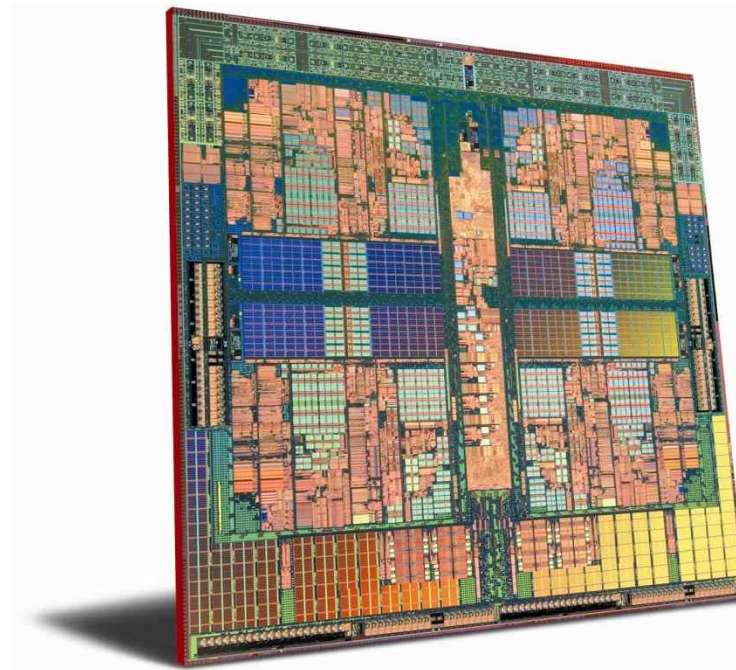
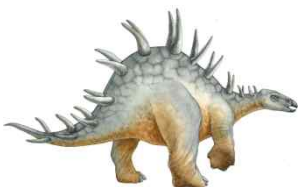
- 동기화
  - 상호배제(mutual exclusion)
  - 사건 순서화(event ordering)
- 메모리 관리
  - 다중포트 메모리(multiport memory): dualport memory
- 신뢰성 및 결함 허용 (fault tolerance)
  - 이주 (migration)







Intel Core 2 Quad(Q6600)

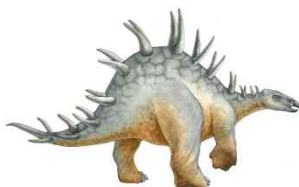
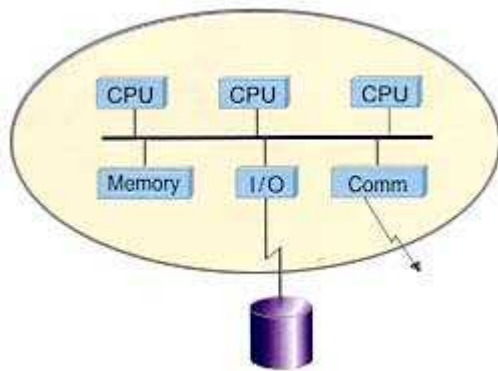


AMD Quad Core CPU(Opteron)

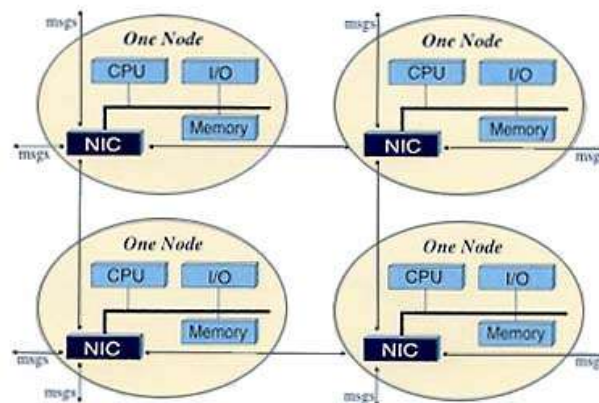


# 병렬 컴퓨터

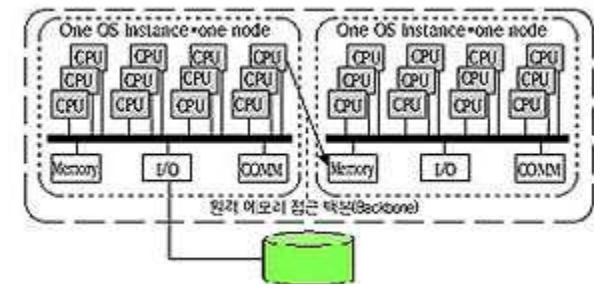
## ■ SMP



## □ MPP (Massive Parallel)



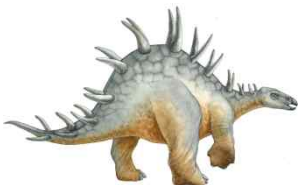
## ■ NUMA (Non-Uniform Memory Access)



# Distributed Systems

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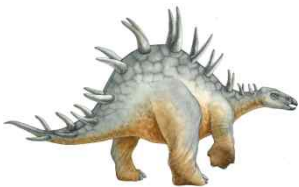
- ❑ Distribute the computation among several physical processors.
- ❑ *Loosely coupled system* – each processor has its own local memory; processors communicate with one another through various communications lines, such as high-speed buses or telephone lines.
- ❑ Advantages of distributed systems.
  - Resources Sharing
  - Computation speed up – load sharing
  - Reliability
  - Communications



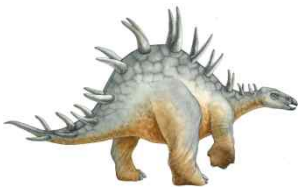
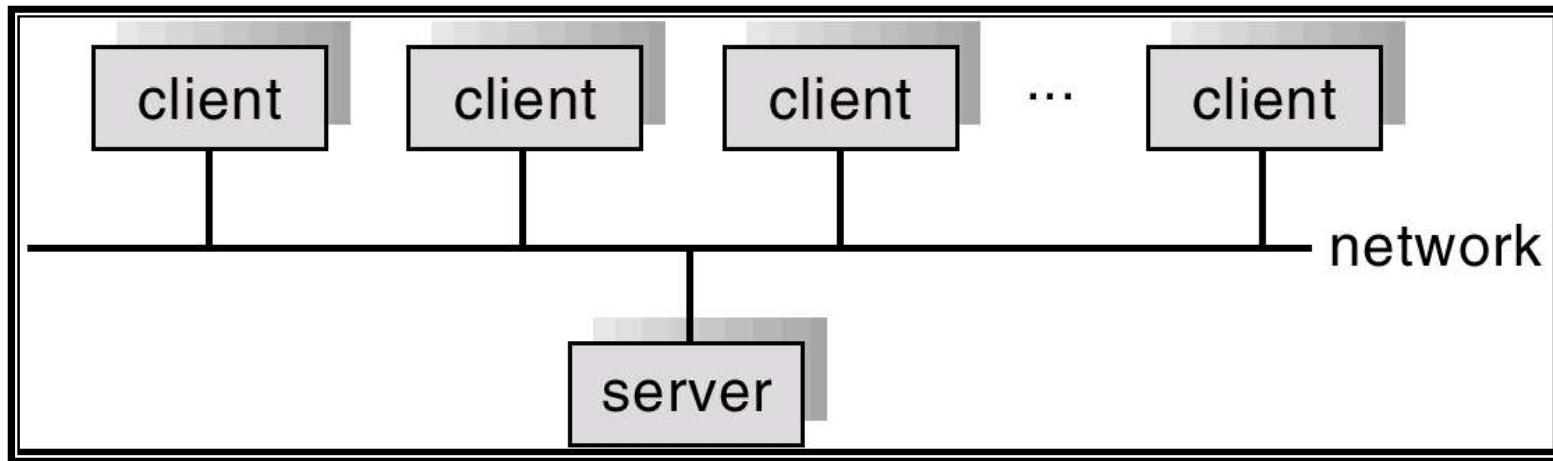
# Distributed Systems (cont)

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- ❑ Requires networking infrastructure.
- ❑ Local area networks (LAN) or Wide area networks (WAN)
- ❑ May be either client-server or peer-to-peer systems.



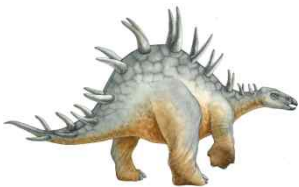
# General Structure of Client-Server



# Real-Time Systems

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- ❑ Often used as a control device in a dedicated application such as controlling scientific experiments, medical imaging systems, industrial control systems, and some display systems.
- ❑ Well-defined fixed-time constraints.
- ❑ Real-Time systems may be either *hard* or *soft* real-time.





# Real-Time Systems (Cont.)

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## □ Hard real-time:

- Secondary storage limited or absent, data stored in short term memory, or read-only memory (ROM)
- Conflicts with time-sharing systems, not supported by general-purpose operating systems.

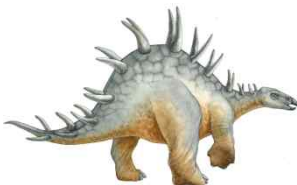
## □ Soft real-time

- Limited utility in industrial control of robotics
- Useful in applications (multimedia, virtual reality) requiring advanced operating-system features.



# Handheld Systems

- Personal Digital Assistants (PDAs)
- Cellular telephones
- Issues:
  - Limited memory
  - Slow processors
  - Small display screens.



# Clustered Systems

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- ❑ Clustering allows two or more systems to share storage.
- ❑ Provides high reliability.
- ❑ *Asymmetric clustering*: one server runs the application while other servers standby.
- ❑ *Symmetric clustering*: all N hosts are running the application.

<http://www.top500.org/>

Desing of Cluster Computer : [http://www.scl.ameslab.gov/Projects/parallel\\_computing/cluster\\_design.html](http://www.scl.ameslab.gov/Projects/parallel_computing/cluster_design.html)  
Examples of Cluster Computer : [http://www.scl.ameslab.gov/Projects/parallel\\_computing/cluster\\_examples.html](http://www.scl.ameslab.gov/Projects/parallel_computing/cluster_examples.html)



# TOP 500

## ■ Top 500

■ [www.top500.org](http://www.top500.org)

**FLOPS** (or **flops** or **flop/s**) is an acronym meaning **F**loating point **O**perations per **S**econd

Computer Performance	
Name	FLOPS
yottaFLOPS	$10^{24}$
zettaFLOPS	$10^{21}$
exaFLOPS	$10^{18}$
petaFLOPS	$10^{15}$
teraFLOPS	$10^{12}$
gigaFLOPS	$10^9$
megaFLOPS	$10^6$
kiloFLOPS	$10^3$

107.55 GFLOPS ([Intel Core i7 980 XE](#))



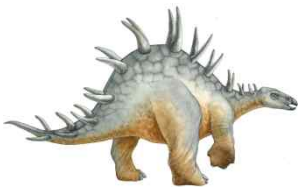
November 2011

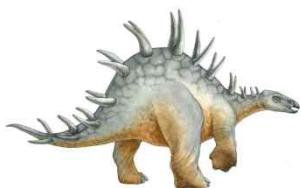
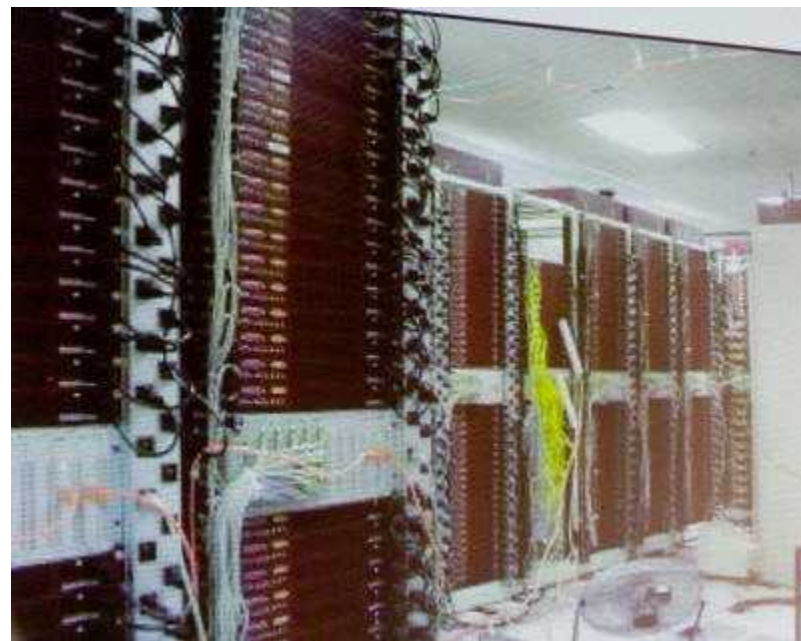
Rank	Site	Computer/Year Vendor	Cores	R <sub>max</sub>	R <sub>peak</sub>	Power
1	RIKEN Advanced Institute for Computational Science (AICS) Japan	K computer, SPARC64 VIIIfx 2.0GHz, Tofu interconnect / 2011 Fujitsu	705024	10510.00	11280.38	12659.9
2	National Supercomputing Center in Tianjin China	NUDT YH MPP, Xeon X5670 6C 2.93 GHz, NVIDIA 2050 / 2010 NUDT	186368	2566.00	4701.00	4040.0
3	DOE/SC/Oak Ridge National Laboratory United States	Cray XT5-HE Opteron 6-core 2.6 GHz / 2009 Cray Inc.	224162	1759.00	2331.00	6950.0
4	National Supercomputing Centre in Shenzhen (NSCS) China	Dawning TC3600 Blade System, Xeon X5650 6C 2.66GHz, Infiniband QDR, NVIDIA 2050 / 2010 Dawning	120640	1271.00	2984.30	2580.0
5	GSIC Center, Tokyo Institute of Technology Japan	HP ProLiant SL390s G7 Xeon 6C X5670, Nvidia GPU, Linux/Windows / 2010 NEC/HP	73278	1192.00	2287.63	1398.6
6	DOE/NNSA/LANL/SNL United States	Cray XE6, Opteron 6136 8C 2.40GHz, Custom / 2011 Cray Inc.	142272	1110.00	1365.81	3980.0
7	NASA/Ames Research Center/NAS United States	SGI Altix ICE 8200EX/8400EX, Xeon HT QC 3.0/Xeon 5570/5670 2.93 Ghz, Infiniband / 2011 SGI	111104	1088.00	1315.33	4102.0
8	DOE/SC/LBNL/NERSC United States	Cray XE6, Opteron 6172 12C 2.10GHz, Custom / 2010 Cray Inc.	153408	1054.00	1288.63	2910.0
9	Commissariat a l'Energie Atomique (CEA) France	Bull bulx super-node S6010/S6030 / 2010 Bull	138368	1050.00	1254.55	4590.0
10	DOE/NNSA/LANL United States	BladeCenter QS22/LS21 Cluster, PowerXCell 8i 3.2 Ghz / Opteron DC 1.8 GHz, Voltaire Infiniband / 2009 IBM	122400	1042.00	1375.78	2345.0
11	National Institute for Computational Sciences/University of Tennessee United States	Cray XT5-HE Opteron Six Core 2.6 GHz / 2011 Cray Inc.	112800	919.10	1173.00	3090.0
12	HWW/Universitaet Stuttgart Germany	Cray XE6, Opteron 6276 16C 2.30 GHz, Cray Gemini interconnect / 2011 Cray Inc.	113472	831.40	1043.94	
13	Forschungszentrum Juelich (FZJ) Germany	Blue Gene/P Solution / 2009 IBM	294912	825.50	1002.70	2268.0
14	National Supercomputing Center in Jinan China	Sunway BlueLight MPP, ShenWei processor SW1600 975.00 MHz, Infiniband QDR / 2011 NRCPCET	137200	795.90	1070.16	1074.0
15	Lawrence Livermore National Laboratory United States	Xtreme-X GreenBlade GB512X, Xeon E5 (Sandy Bridge - EP) 8C 2.60GHz, Infiniband QDR / 2011 Abbro	46208	773.70	961.13	924.2

# Top 1 : K Computer in Japan



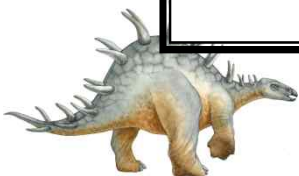
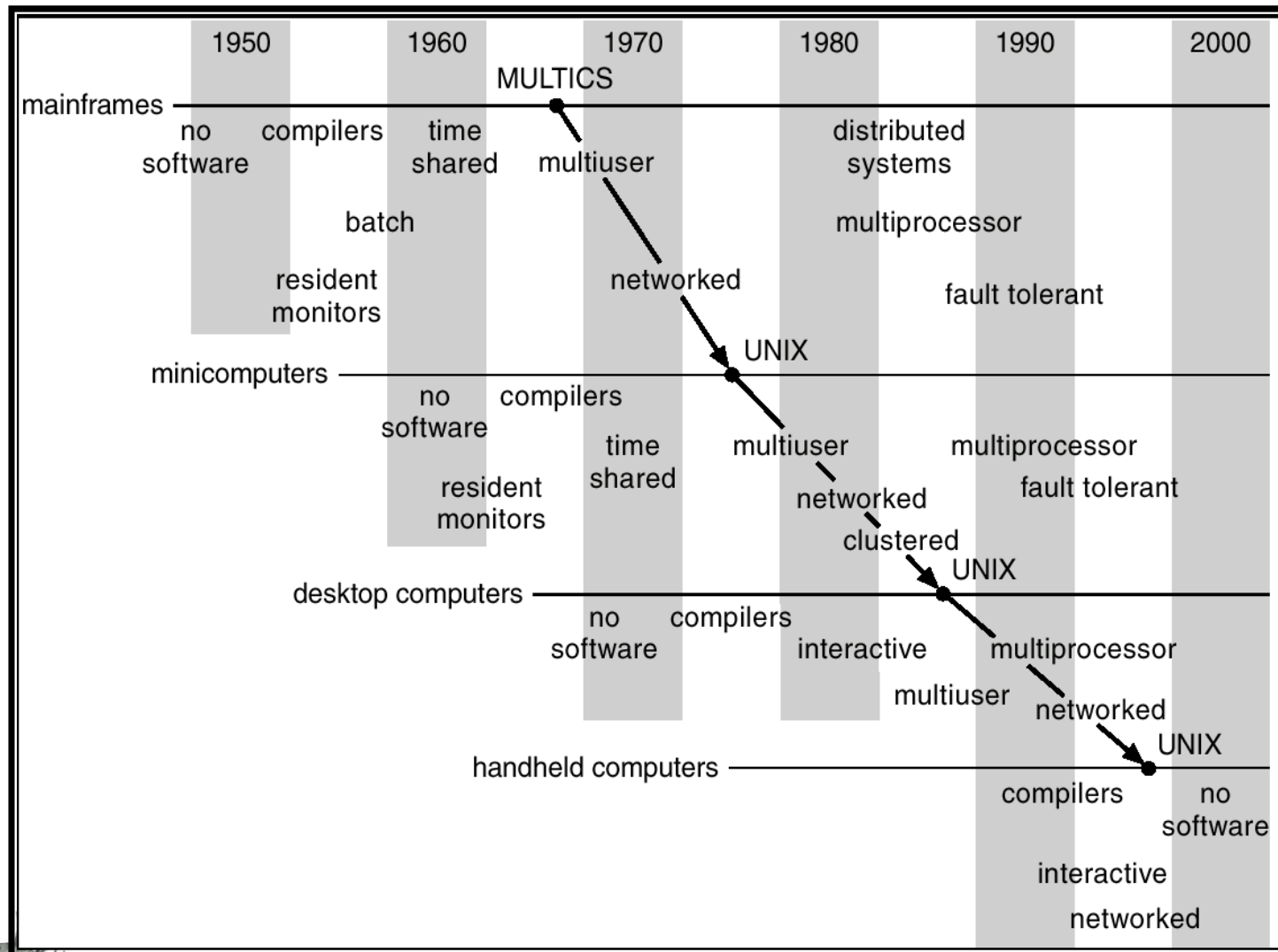








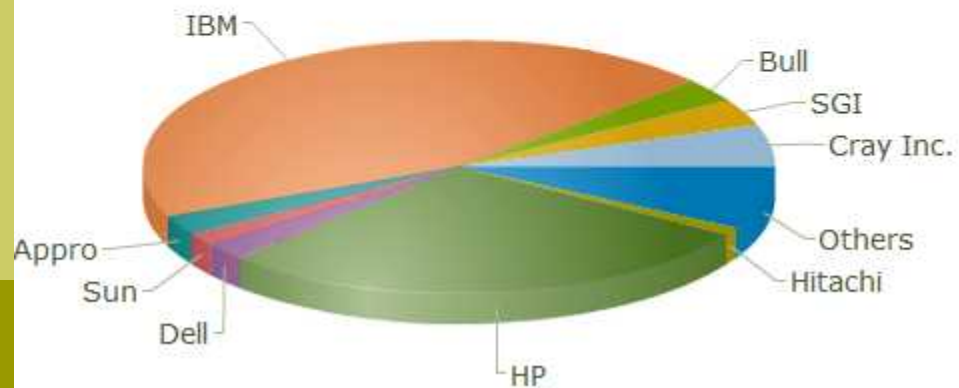
# Migration of Operating-System Concepts and Features



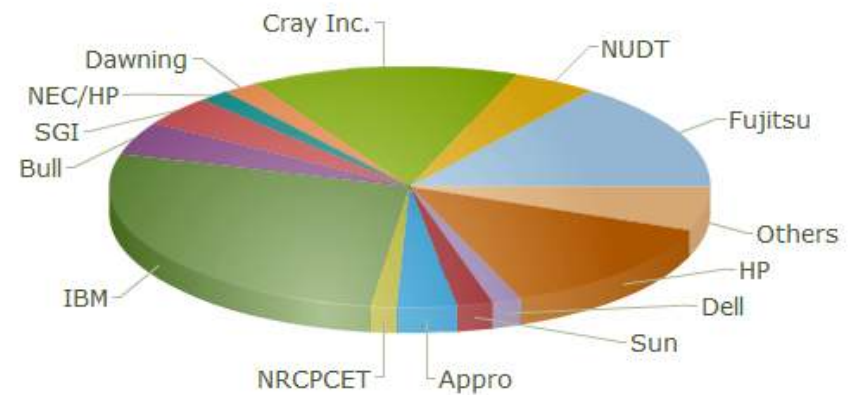


# Systems and Vendors in TOP 500

Vendors / Systems  
November 2011

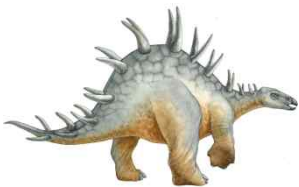
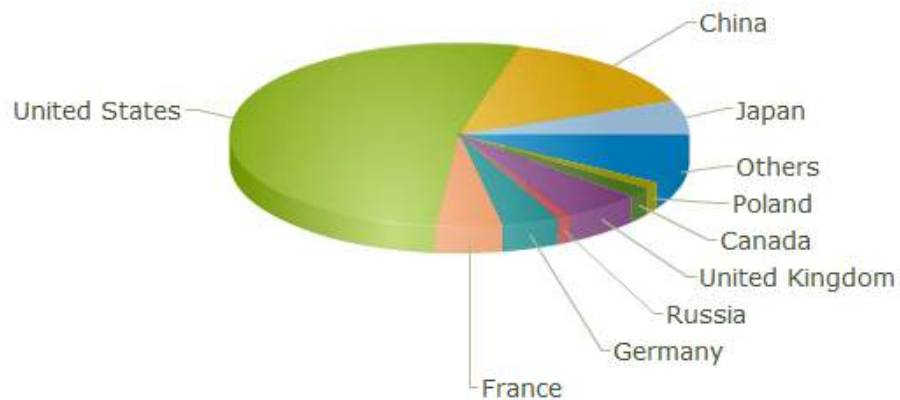


Vendors / Performance  
November 2011

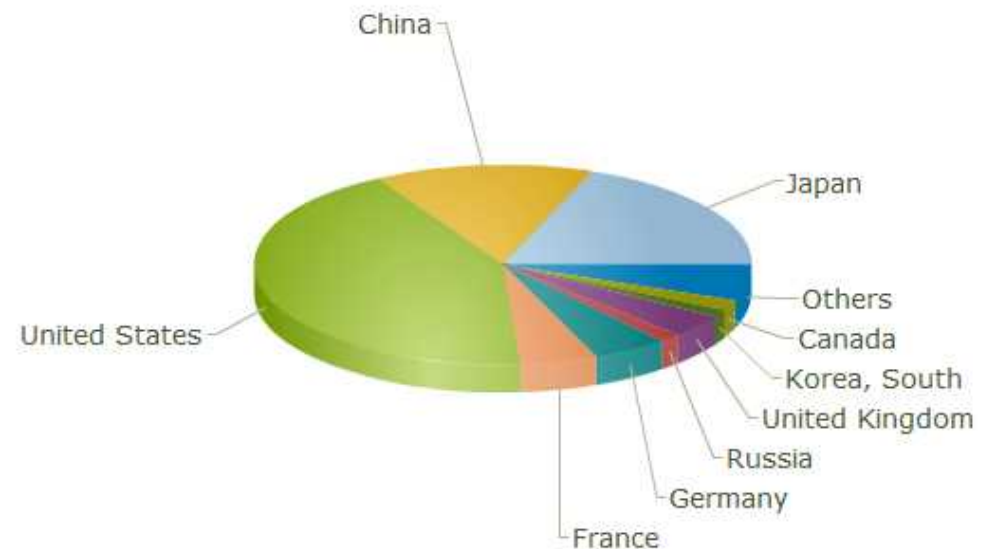


# Systems and Vendors in TOP 500

Countries / Systems  
November 2011

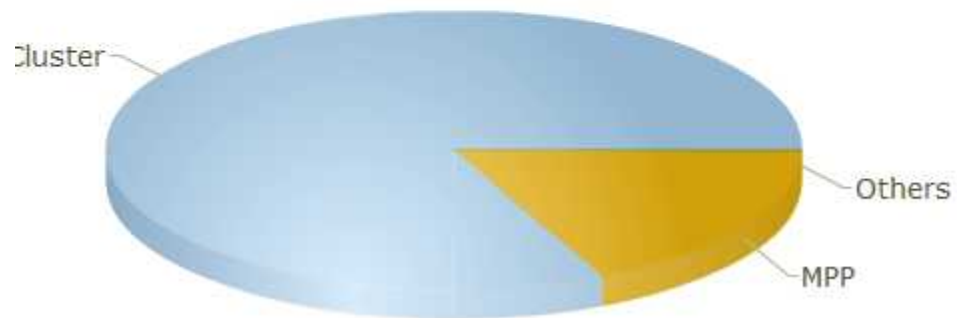


Countries / Performance  
November 2011

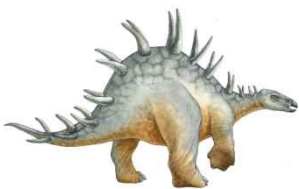
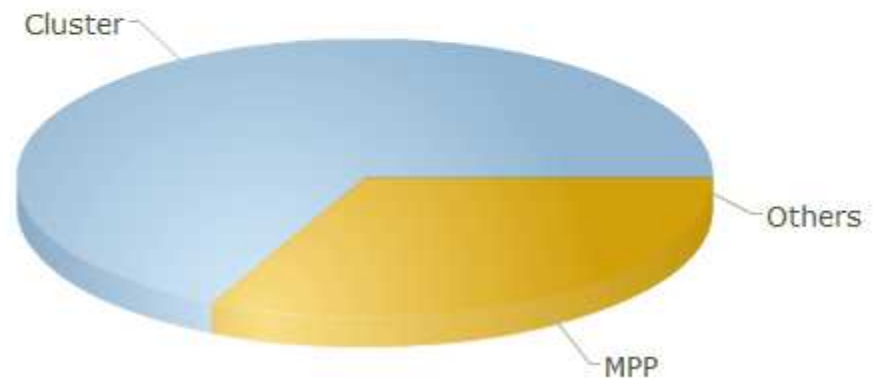


# Architecture in TOP 500

Architecture / Systems  
November 2011

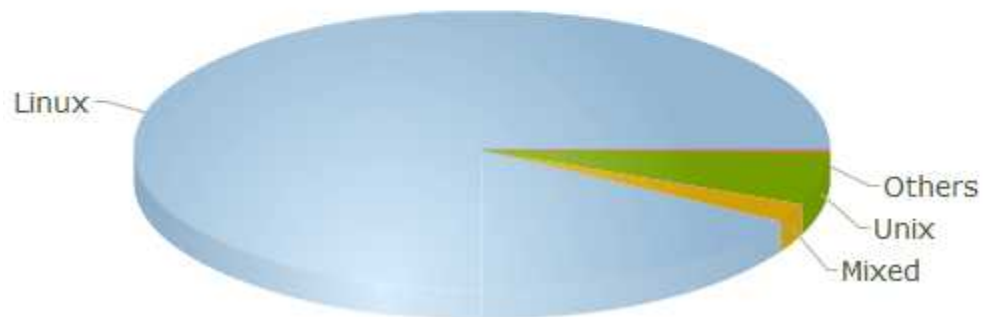


Architecture / Performance  
November 2011

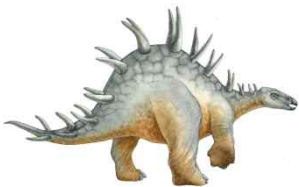


# Current OS in TOP 500

Operating system Family / Systems  
November 2011



Operating system Family / Performance  
November 2011



# Computer System Architecture

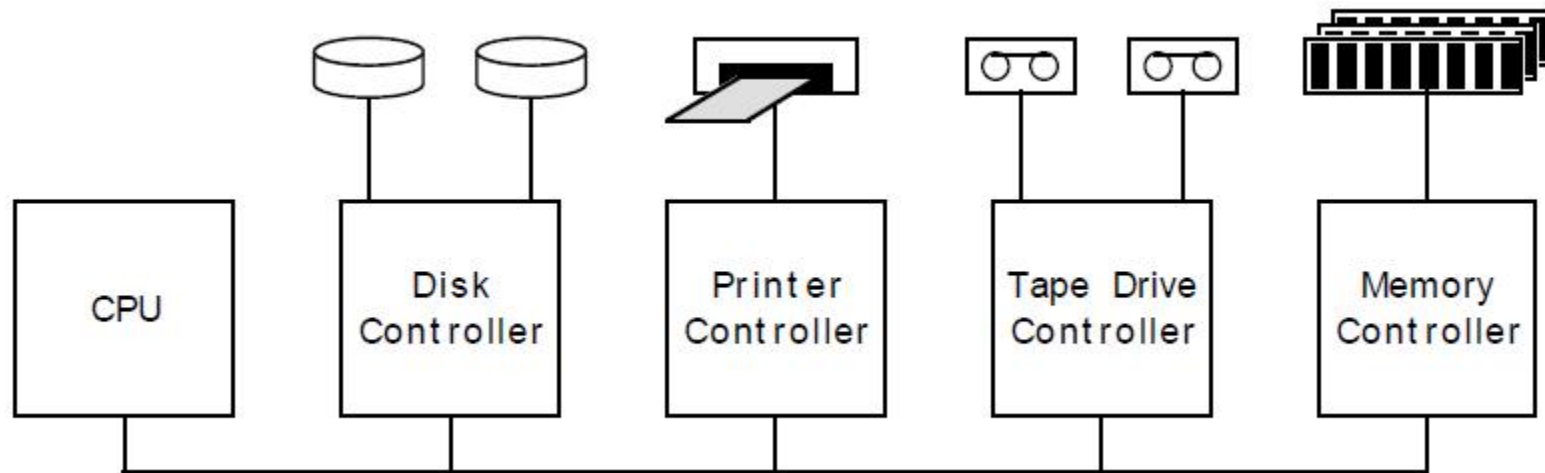
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# Computer-System Architecture

## ■ Computer-system operation

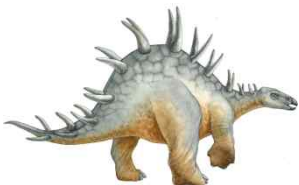
- 하나 또는 그 이상의 **CPUs, device controllers**이 공유 메모리에 대한 접근을 제공한 공통 **bus**에 접속됨
- **CPUs and devices**들이 **system bus**와 **memory cycle**을 위해 경쟁



# Computer-System Operation

- I/O devices와 CPU는 concurrently 실행할 수 있다
- 각 device controller 는 특정 device type을 갖는다
- Each device controller는 **local buffer**를 갖는다
  - CPU/IO간 동작
    - CPU는 data를 from/to main memory to/from local buffers 이동시킨다
    - I/O는 device들로부터 controller의 local buffer로 이동시킨다

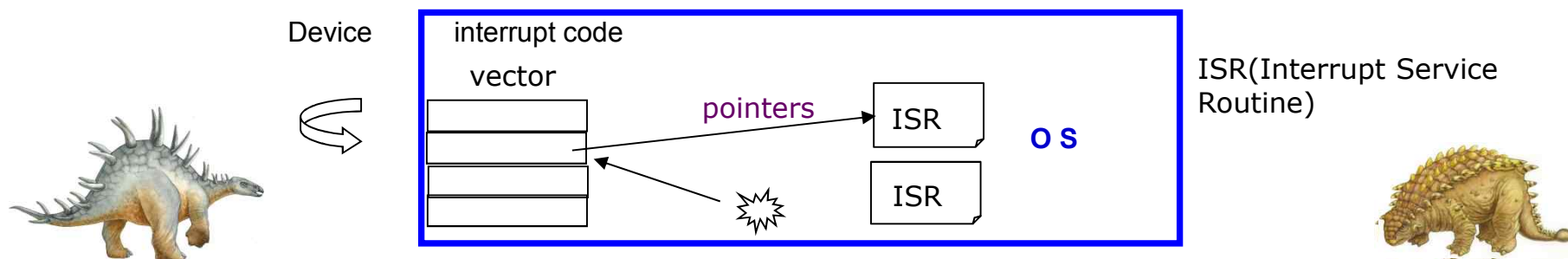
Why not connect all I/O devices directly to CPU? Why not... memory...?



# Common Functions of Interrupts

현대의 운영체제는 **interrupt driven** 방식을 사용한다!

- Interrupt는 일반적으로 **interrupt vector**를 통해 제어를 interrupt service routine으로 transfer한다. interrupt vector는 모든 service routine의 address를 포함하고 있다
- 'lost interrupt'를 방지하기 위해서 하나의 interrupt가 process 중일 때는 다른 interrupt는 사용할 수 없다
  - *error 또는 사용자 request에 의해 발생하는 software-generated interrupt를 **trap**이라고 한다.*
- An operating system is **interrupt driven**.

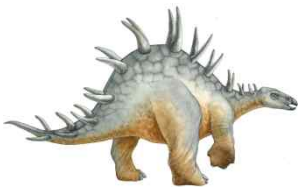




# Interrupt Handling

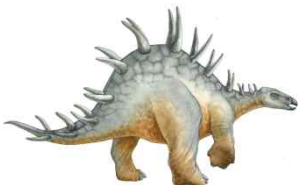
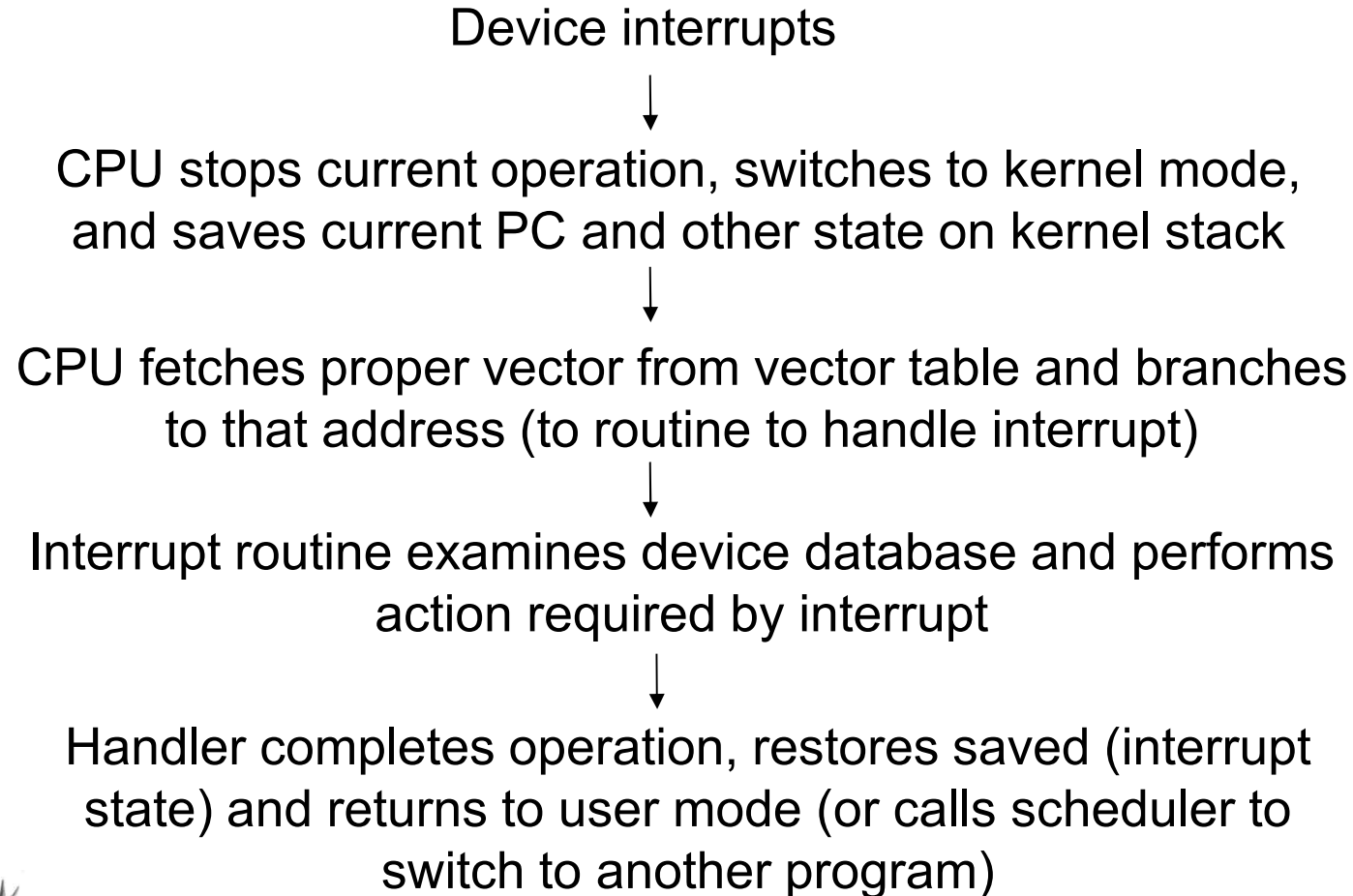
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- 1. The operating system preserves the state of the CPU by storing **registers** and the **program counter**.
- 2. 어떤 **type**의 **intterrupt**가 발생했는지를 결정한다
  - *polling*
  - *vectored* interrupt system
- 3. 분리된 **code segment**를 통해 각 **interrupt**의 **type**별로 어떤 **action**이 수행되어야 하는지를 결정한다



# I/O Structure

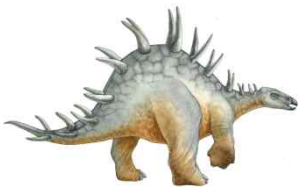
## I/O Interrupt의 수행순서



# Computer-System Operation

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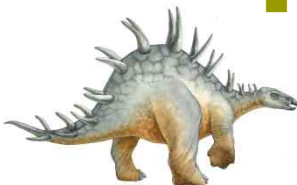
- Terminology
  - Synchronous I/O
    - CPU execution waits while I/O proceeds
  - Asynchronous I/O
    - I/O proceeds concurrently with CPU execution



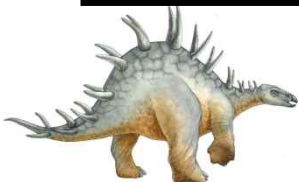
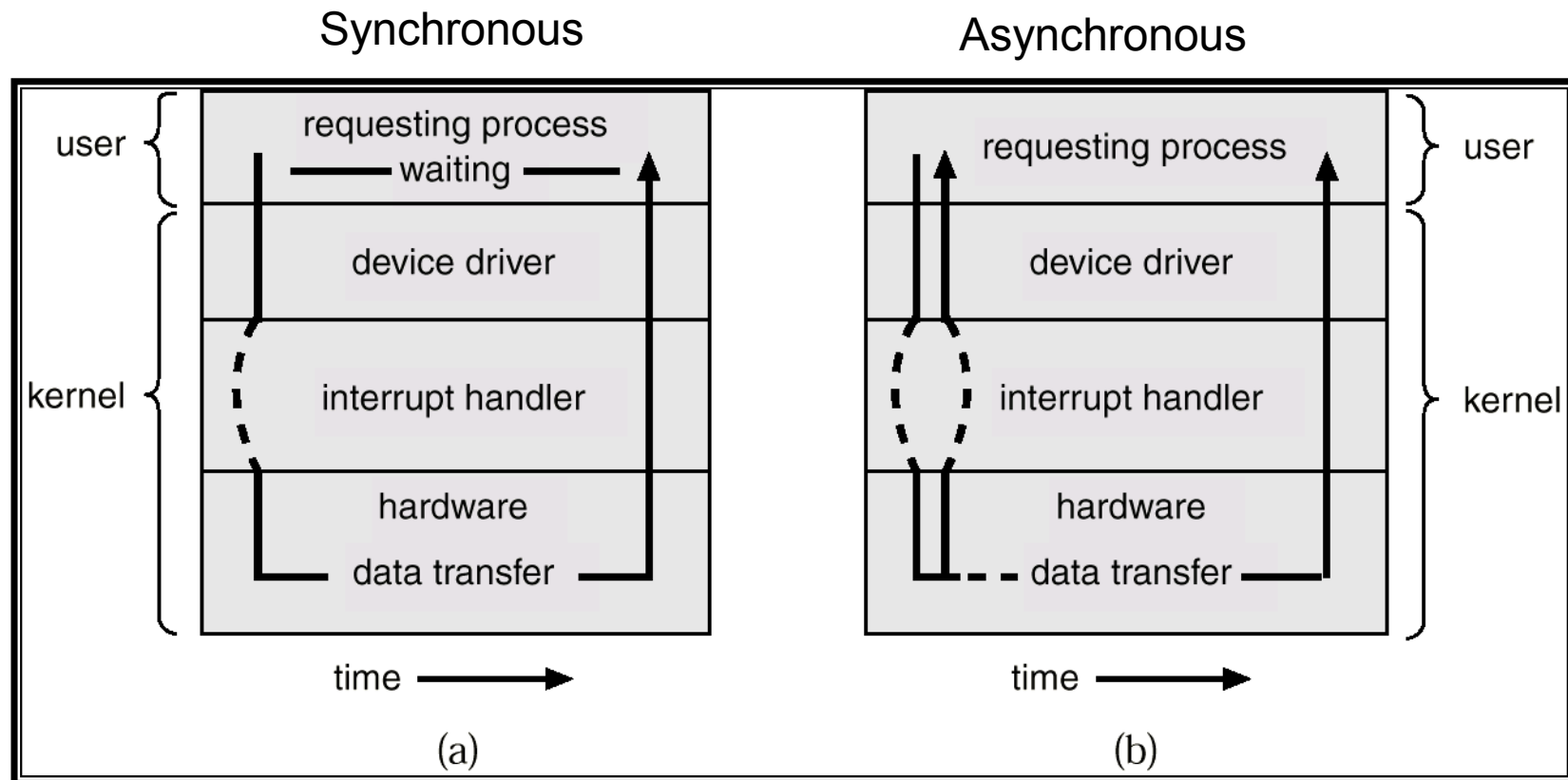
# I/O Structure

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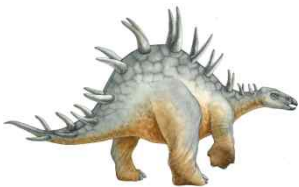
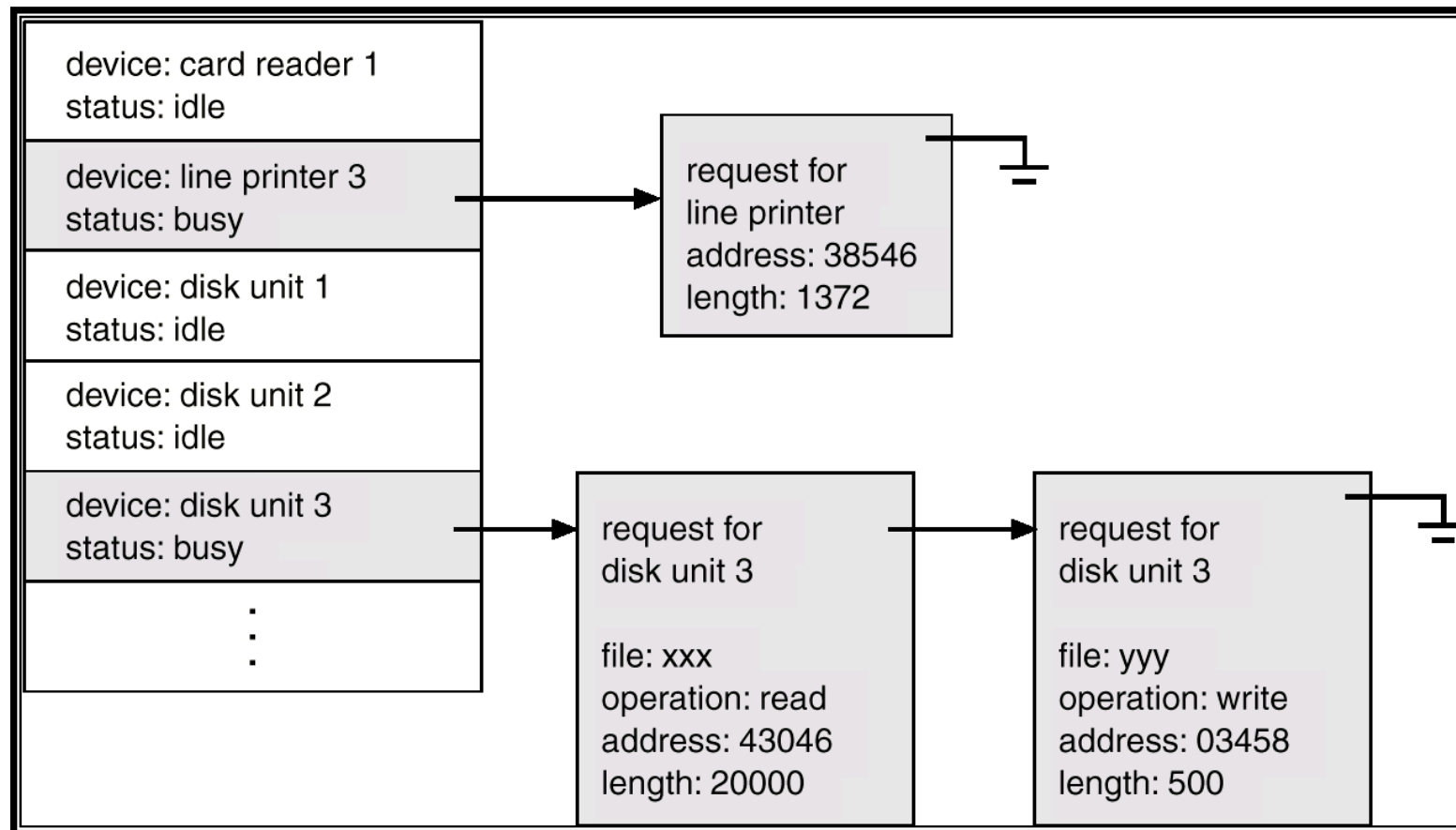
- ❑ After I/O starts, control returns to user program only upon I/O completion. (**Synchronous**)
  - Wait instruction idles the CPU until the next interrupt
  - Wait loop (contention for memory access).
  - At most one I/O request is outstanding at a time, no simultaneous I/O processing.
  
- ❑ After I/O starts, control returns to user program without waiting for I/O completion. (**Asynchronous**)
  - *System call* – request to the operating system to allow user to wait for I/O completion.
  - **Device-status table** contains entry for each I/O device indicating its type, address, and state.
  - Operating system indexes into I/O device table to determine device status and to modify table entry to include interrupt.



# Two I/O Methods



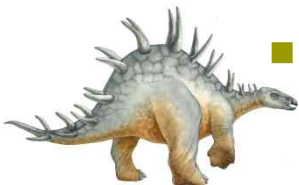
# Device-Status Table



# Direct Memory Access Structure

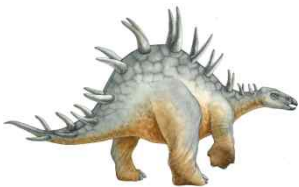
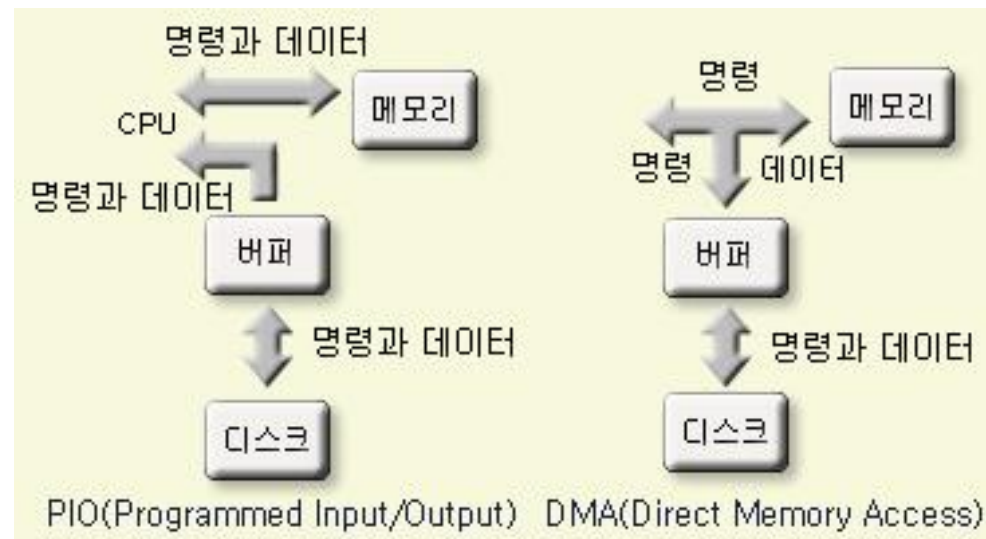
DMA = Direct Memory Access

- 디스크, 테이프, 또는 통신 네트워크와 같은 high-speed I/O device들이 memory speed에 근접하게 정보를 전송하는 경우 사용됨
  - 즉, 고속 I/O에 의해 빈번한 interrupt가 호출되는 것을 줄이고 고속으로 데이터를 전송하기 위해 사용
- DMA는 Device controller가 데이터들의 block들을 buffer 저장장소에서 main memory로 CPU intervention 없이 전송할 수 있게 함
- Only one interrupt is generated per block, rather than the one interrupt per byte.
  - cycle stealing에 의해 CPU로부터 memory cycle을 훔쳐서 실행하므로 DMA전송 동안 CPU실행이 늦어질 수 있음



# Direct Memory Access Structure

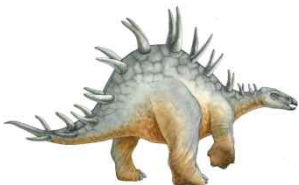
## □ DMA의 실행 구조



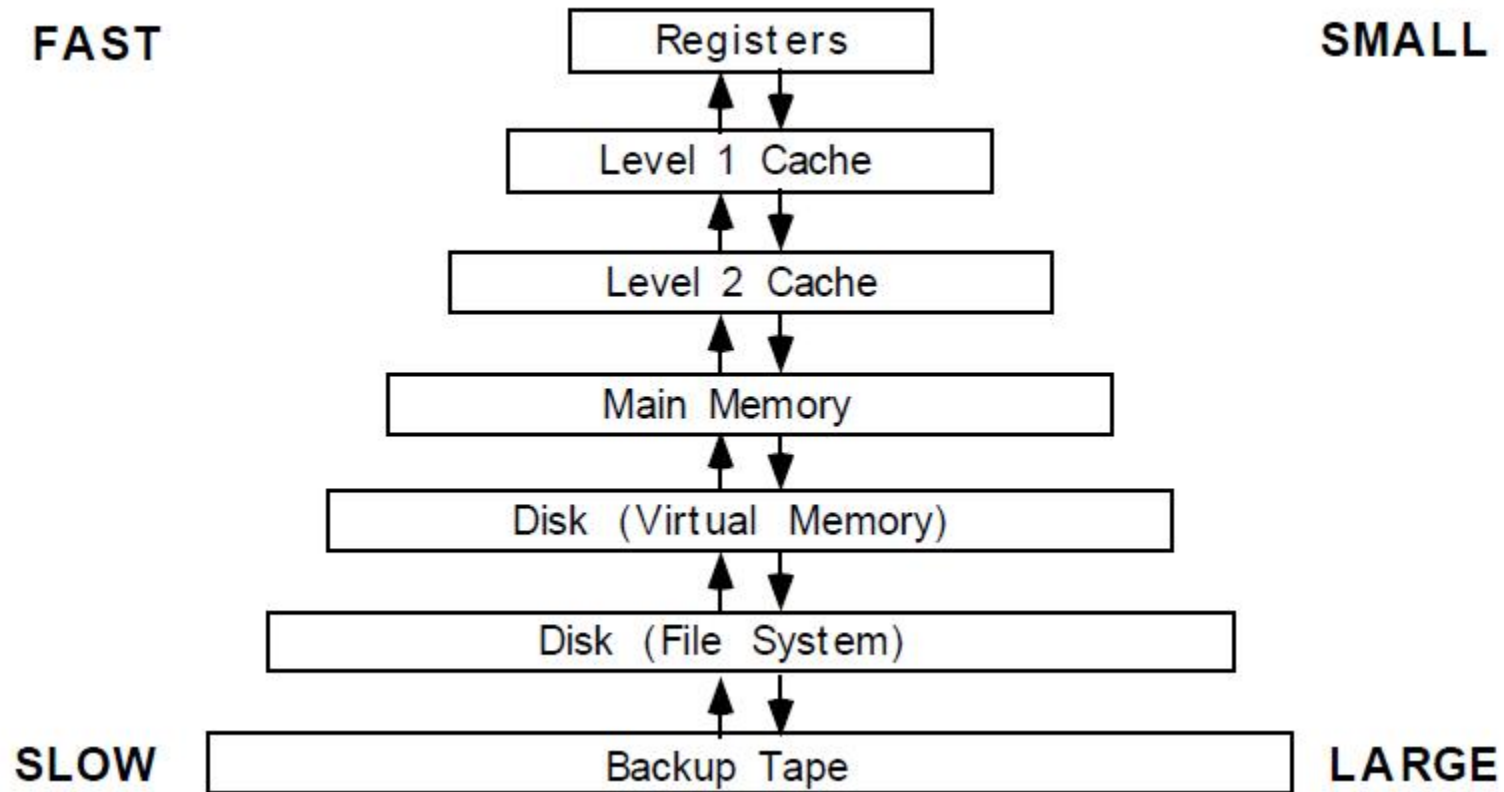


# Storage Structure

- ❑ Main memory – only large storage media that the CPU can access directly.
  - DRAM(Dynamic RAM) : data refresh 필요
  - SRAM(Static RAM) : 불필요
  - SDRAM(Synchronous DRAM) : data bus와 동기화(PC133)
- ❑ Secondary storage – extension of main memory that provides large nonvolatile storage capacity.
  - Magnetic disks – rigid metal or glass platters covered with magnetic recording material
    - ❑ Disk surface is logically divided into *tracks*, which are subdivided into *sectors*.
    - ❑ The *disk controller* determines the logical interaction between the device and the computer.

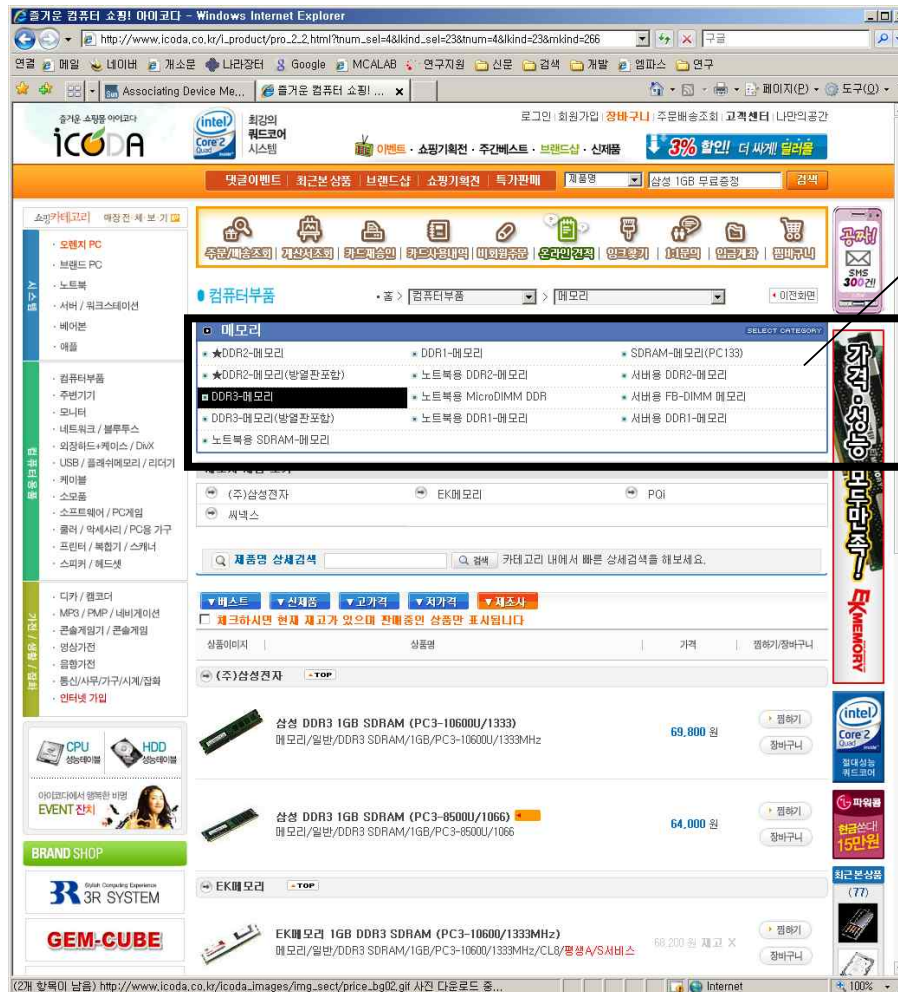


# Storage-Device Hierarchy





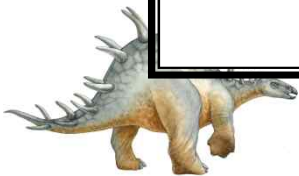
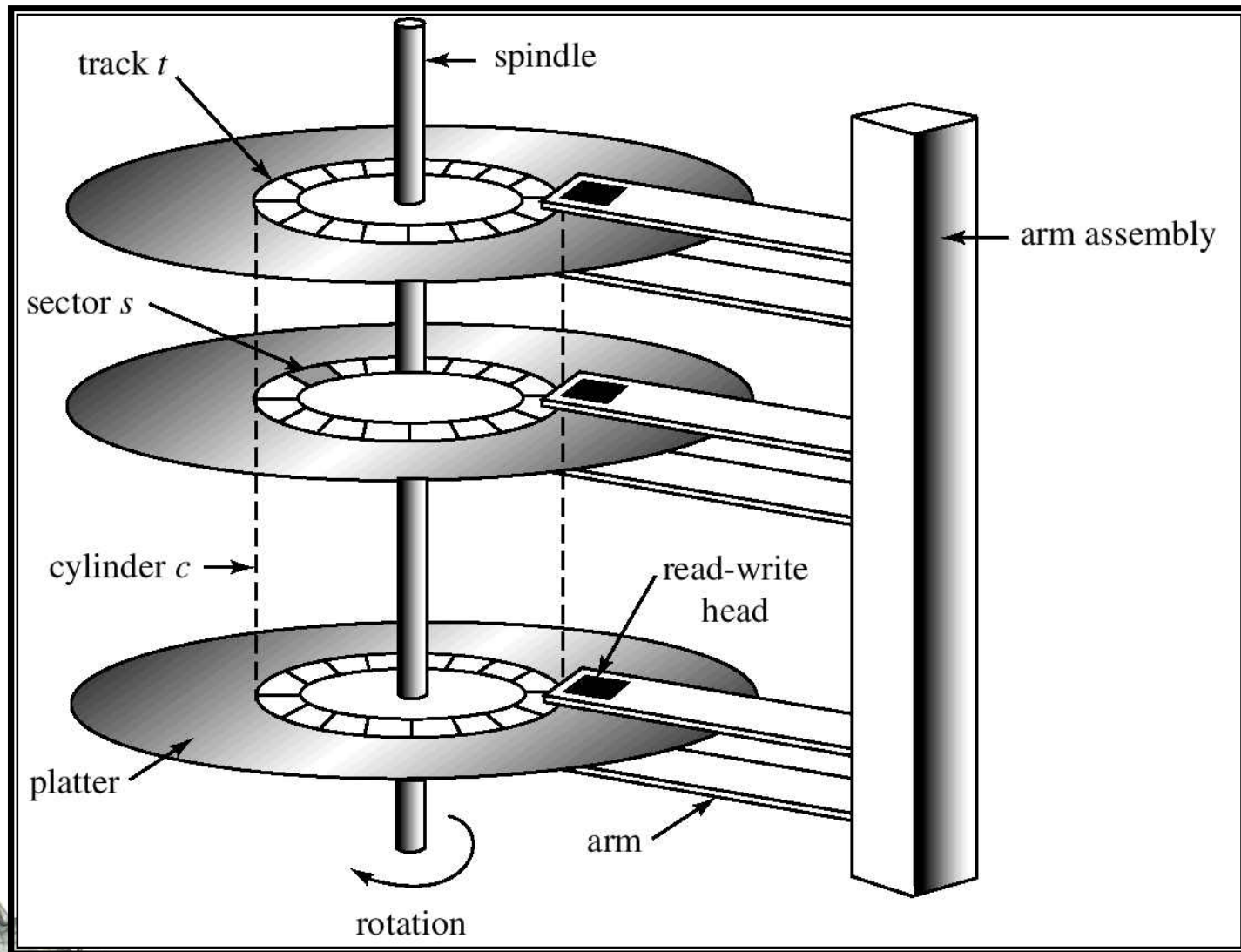
# Storage Structure



현재의  
PC 메모리



# Moving-Head Disk Mechanism





# Moving-Head Disk Mechanism



Seagate SATA2 320G (7200.10/16M) 정품

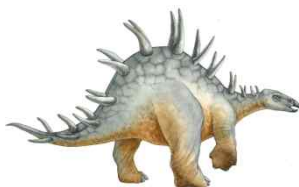
등록	업체	최저가
703월	247	76,000
703월	205	112,000
703월	173	62,000
703월	201	74,000
702월	209	76,000
706월	239	50,000
05년	246	63,000
710월	190	48,000
712월	218	114,000
709월	186	83,000
05년	209	61,000
707월	238	76,000
702월	162	115,000



Seagate SATA2 320G (7200.10/16M) 정품

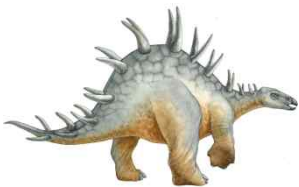
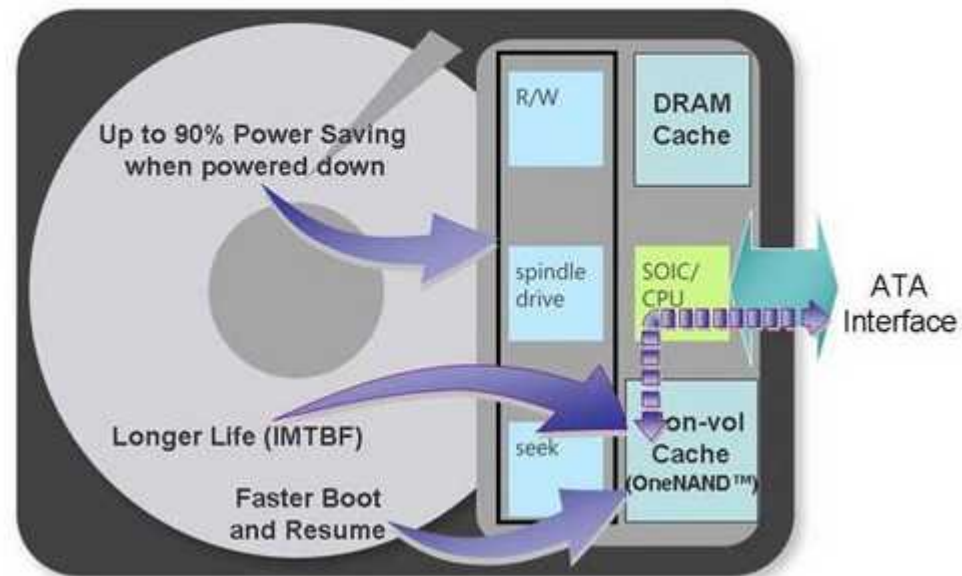
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710월	190	48,000
712월	218	114,000
709월	186	83,000
05년	209	61,000
707월	238	76,000
702월	162	115,000

제조사	시게이트
원산지	한국전지공장
제품명	Seagate Barracuda 7200.10
형식	SATA II 하드디스크
용량	320GB
원판 회전 속도	7,200rpm
캐시 메모리	16MB
외부 최대 전송 속도	3.0Gb/s
평균 대기 시간	4.16ms
헤드	4개
플러터	160GB 2장
연간 오류율	0.34%
소음	아주 조용할 때 2.7bels, 아주 시끄러울 때 3.0bels (bels는 음향 출력 단위)
전원관리	탐색 평균 12.6W 작동 평균 13.0W 유휴 평균 9.3W
보증기간	5년
크기	101.6 x 146.9 x 26.1 (mm)
특징	- 작동환경 조건이 바뀌면 알아서 헤드와 플러터의 거리를 조절하는 Adaptive Fly Height - 불규칙한 디스크 표면에 대비해 작동시 플러터 전체를 거쳐 드라이브 헤드들 통과해 집적도와 신뢰도를 높이는 Clean Sweep - 플러터가 빨리 돌아갈 필요없이 처리량을 늘리고 용량과 신뢰도를 높인 수직기록방식



# Hybrid HDD

## Hybrid Drive Benefits



# Storage Structure:SSD



**초고속 전송속도**  
**충격에도 끄떡없는 단단한 내구성**  
**1W의 소비전력**

**제품명 : 2.5" 64GB SSD SATA-2 SLC**  
**제조사 : 삼성전자**  
**규격 : 2.5" Type(100.2 X 70.0 X 9.5mm)**  
**인터페이스 : S-ATA2 (SAS, S-ATA1 호환)**  
**동작속도 : 읽기속도(평균)-100MB/s**  
**쓰기속도(평균)-80MB/s**  
**칩구성 : SLC**  
**중량 : 73g(MAX)**  
**MTBF : 2,000,000 시간**  
**작동온도 : 0~70도**  
**소비전력 : 1W**  
**Operating Vibration : 20G(10~2000Hz)**  
**Shock resistance : 1,500G for 0.5ms**  
**Acoustic Noise : None**





# Storage Hierarchy

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- ❑ Storage systems organized in hierarchy.
  - Speed
  - Cost
  - Volatility
  
- ❑ *Caching* – copying information into faster storage system; main memory can be viewed as a last *cache* for secondary storage.

